

## Design and Implementation Based On Amba4.0 Of Apb Bridge

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**Abstract:** ARM introduced the Advanced Microcontroller Bus Architecture (AMBA) 4.0 specifications which includes Advanced eXtensible Interface (AXI) 4.0. AMBA bus protocol has become the de facto standard SoC bus. That means more and more existing IPs must be able to communicate with AMBA4.0 bus. Based on AMBA 4.0 bus, we designed an Intellectual Property (IP) core of Advanced Peripheral Bus (APB) Bridge, which translates the AXI4.0-lite transactions into APB 4.0 transactions. The bridge provides an interfaces between the high-performance AXI bus and low-power APB domain.

**Keywords:** SoC, AMBA, AXI, APB

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### I. Introduction

There are many companies that develop core IP for SoC products. The interfaces to these cores can differ from company to company and can sometimes be proprietary in nature. The SoC developer then must expend time, effort, and money to create “bridge” or “glue” logic that allows all of the cores inside the SoC to communicate properly with each other. Incompatible interfaces are thus barriers to both IP developers and SoC developers.

Integrated circuits have entered the era of System-on-a-Chip (SoC), which refers to integrating all components of a computer or other electronic system into a single chip. It may contain digital, analog, mixed-signal, and often radio-frequency functions – all on a single chip substrate. With the increasing design size, IP is an inevitable choice for SoC design. And the widespread use of all kinds of IPs has changed the nature of the design flow, making On-Chip Buses (OCB) essential to the design.

Of all OCBs existing in the market, the AMBA bus system is widely used as the de facto standard SoC bus. On March 8, 2010, ARM announced availability of the AMBA 4.0 specifications. As the de facto standard SoC bus, AMBA bus is widely used in the high-performance SoC designs..

ARM introduced the Advanced Microcontroller Bus Architecture (AMBA) 4.0 specifications in March 2010, which includes Advanced extensible Interface (AXI) 4.0. AMBA bus protocol has become the de facto standard SoC bus. That means more and more existing IPs must be able to communicate with AMBA 4.0 bus. Based on AMBA 4.0 bus, This design is an Intellectual Property (IP) core of AXI(Advanced extensible Interface) Lite to APB(Advanced Peripheral Bus) Bridge, which translates the AXI4.0-lite transactions into APB 4.0 transactions. The bridge provides interfaces between the high-performance AXI bus and low-power APB domain.

### II. Literature Review

Advanced Microcontroller Bus Architecture (AMBA) specification defines an on chip communications standard for designing high-performance embedded microcontrollers. AMBA has 4 versions as follows

1. VER1.0 (ASB & APB)
2. VER 2.0 (AHB)
3. VER 3.0 (AXI, ATB)
4. VER 4.0 (AXI 4, AXI LITE, AXI STREAM (AXI))

AMBA 4.0 specification buses/interfaces

1. Advanced eXtensible Interface (AXI)
2. Advanced High-performance Bus (AHB)
3. Advanced System Bus (ASB)
4. Advanced Peripheral Bus (APB)
5. Advanced Trace Bus (ATB)

In this project these are to be used Advanced eXtensible Interface (AXI4-Lite) & Advanced Peripheral Bus (APB) because these are high bandwidth data transfer between high performance devices like processor, DMA, RAM etc..., and Peripheral devices.



### 3.3. Handshake Mechanism of AXI & APB

In AXI 4.0 specification, each channel has VALID and READY signals for handshaking. The source asserts VALID when the control information or data is available. The destination asserts READY when it can accept the control information or data. Transfer occurs only when both the VALID and READY are asserted. Figure3 Shows all possible cases of VALID/READY handshaking. Note that when source asserts VALID, the corresponding control information or data must also be available at the same time. The arrows in Figure. Indicate when the transfer occurs. A transfer takes place at the positive edge of clock. Therefore, the source needs a register input to sample the READY signal. In the same way, the destination needs a register input to sample the VALID signal. Considering the situation of last Figure, we assume the source and destination use output registers instead of combination circuit, they need one cycle to pull low VALID/READY and sample the VALID/READY again at T4 cycle. When they sample the VALID/READY again at T4, there should be another transfer which is an error. Therefore source and destination should use combinational circuit as output. In short, AXI protocol is suitable register input and combinational output circuit.

The APB Bridge buffers address, control and data from AXI4-Lite, drives the APB peripherals and returns data and response signal to the AXI4-Lite. It decodes the address using an internal address map to select the peripheral. The bridge is designed to operate when the APB and AXI4-Lite have independent clock frequency and phase. For every AXI channel, invalid commands are not forwarded and an error response generated. That is once a peripheral accessed does not exist, the APB Bridge will generate DE CERR as response through the response channel (read or write). And if the target peripheral exists, but asserts PSLVERR, it will give a SLVERR response.

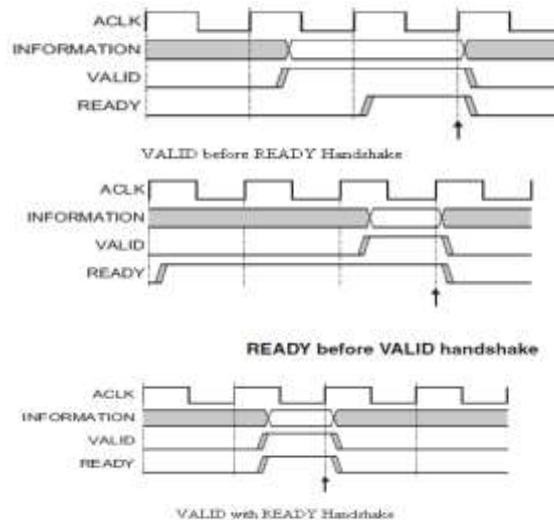


Figure3. Waveforms for handshaking mechanism

### 3.4 Finite State Machine

A finite-state machine (FSM) or finite-state automaton (plural: automata), or simply a state machine, is a mathematical model used to design computer programs and digital logic circuits. It is conceived as an abstract machine that can be in one of a finite number of states. The machine is in only one state at a time; the state it is in at any given time is called the current state. It can change from one state to another when initiated by a triggering event or condition, this is called a transition. A particular FSM is defined by a list of the possible transition states from each current state, and the triggering condition for each transition.

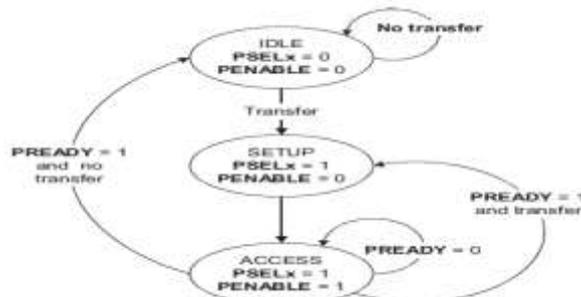


Figure4. Operational activity of the APB.

The state machine operates through the following states:

**IDLE:** This is the default state of the APB.

**SETUP:** When a transfer is required the bus moves into the SETUP state, where the appropriate select signal, **PSELx**, is asserted. The bus only remains in the SETUP state for one clock cycle and always moves to the ACCESS state on the next rising edge of the clock.

**ACCESS:** The enable signal, **PENABLE**, is asserted in the ACCESS state. The address, writes, select, and write data signals must remain stable during the transition from the SETUP to ACCESS state.

Exit from the ACCESS state is controlled by the **PREADY** signal from the slave:

- If **PREADY** is held LOW by the slave then the peripheral bus remains in the ACCESS state.
- If **PREADY** is driven HIGH by the slave then the ACCESS state is exited and the bus returns to the IDLE state if no more transfers are required.

### 3.5 Simulation

The Timing Diagram shows the AXI4Lite to APB bridge operation for various read and write transfers. It shows that when both read and write requests are active, read is given more priority than write

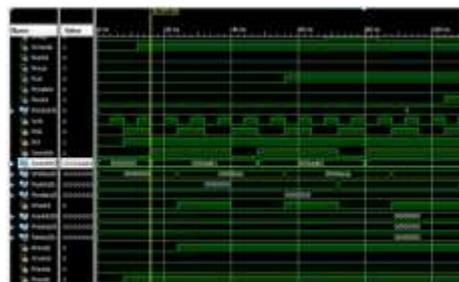


Figure5.Write side

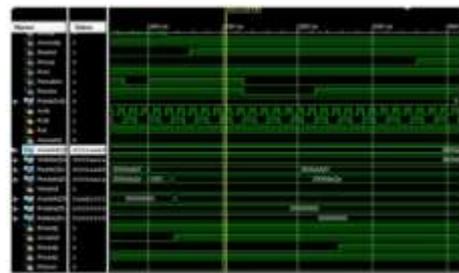


Figure6.Read side

### 3.6 Synthesis Result

---- Source Parameters

Input File Name : "apb\_bridge\_cha.prj"

Input Format : mixed

Ignore Synthesis Constraint File : NO

---- Target Parameters

Output File Name : "apb\_bridge\_cha"

Output Format : NGC

Target Device : xc3s500e-4-fg320

---- Source Options

Top Module Name : apb\_bridge\_cha

Automatic FSM Extraction : YES

FSM Encoding Algorithm : Auto

Safe Implementation : No

FSM Style : lut

RAM Extraction : Yes

RAM Style : Auto

ROM Extraction : Yes

Mux Style : Auto

Decoder Extraction : YES

Priority Encoder Extraction : YES

Shift Register Extraction : YES

Logical Shifter Extraction : YES  
XOR Collapsing : YES  
ROM Style : Auto  
Mux Extraction : YES  
Resource Sharing : YES  
Asynchronous To Synchronous : NO  
Multiplier Style : auto  
Automatic Register Balancing : No  
---- Target Options  
Add IO Buffers : YES  
Global Maximum Fanout : 500  
Add Generic Clock Buffer(BUFG) : 24  
Register Duplication : YES  
Slice Packing : YES  
Optimize Instantiated Primitives : NO  
Use Clock Enable : Yes  
Use Synchronous Set : Yes  
Use Synchronous Reset : Yes  
Pack IO Registers into IOBs : auto  
Equivalent register Removal : YES

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#### HDL Synthesis Report

##### Macro Statistics

# RAMs : 3  
256x32-bit dual-port RAM : 3  
# Counters : 6  
8-bit up counter : 6  
# Registers : 69  
1-bit register : 49  
32-bit register : 10  
4-bit register : 4  
8-bit register : 6  
# Latches : 3  
1-bit latch : 3  
# Comparators : 3  
8-bit comparator equal : 3  
# Multiplexers : 1  
32-bit 4-to-1 multiplexer : 1  
# Xors : 12  
1-bit xor2 : 6  
7-bit xor2 : 6

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#### Advanced HDL Synthesis Report

##### Macro Statistics

# RAMs : 3  
256x32-bit dual-port distributed RAM : 3  
# Counters : 6  
8-bit up counter : 6  
# Registers : 433  
Flip-Flops : 433  
# Latches : 3  
1-bit latch : 3  
# Comparators : 3  
8-bit comparator equal : 3  
# Multiplexers : 1  
32-bit 4-to-1 multiplexer : 1  
# Xors : 12  
1-bit xor2 : 6  
7-bit xor2 : 6

\* Final Report \*

#### TIMING REPORT

Timing Summary:

Speed Grade: -4

Minimum period: 5.254ns (Maximum Frequency: 190.331MHz)

Minimum input arrival time before clock: 5.198ns

Maximum output required time after clock: 4.394ns

Maximum combinational path delay: No path found

CPU : 21.40 / 21.99 s | Elapsed : 21.00 / 22.00 s

Total memory usage is 222952 kilobytes

Number of errors : 0 ( 0 filtered)

Number of warnings : 24 ( 0 filtered)

Number of infos : 14 ( 0 filtered)

#### IV. Conclusion

The Implementation APB Bridge is designed in this project. Verilog has been used for implementing the bridge. The bridge has the low cost interface optimized for minimal power consumption and reduced interface complexity.

An implementation of AXI4-Lite to APB bridge which has the following features:

- 32-bit AXI slave and APB master interfaces.
- PCLK clock domain completely independent of ACLK clock domain.
- Support up to 16 APB peripherals.
- Support the PREADY signal which translate to wait states on AXI.
- An error on any transfer results in SLVERR Bus the AXI read/write response.
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