# Periodic Solutions of abstract neutral functional differential equations

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Abstract

We charaterize the existence of periodic solutions for a class of abstract neutral functional differential equations described in

the form:

$$\frac{d}{dt}x(t) = A[x(t) - Bx(t-r)] + L(x_t) + f(t), t \in R$$
 (1)

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#### 1. Introduction:

Let X be a Banach space endowed with a norm |.| and r be non negative real number.

The main objective of this paper is to study the existence of periodic solutions for the class of linear abstract neutral differential equations (1):

C = C([-r,0]; X) be the Banach space of continuous functions mapping the interval [-r,0] into X. the function  $x_t$  given by  $x_t(\theta) = x(t+\theta)$  for  $\theta$  in appropriate domain, denotes the segment or the "history" of the function x(.) at t.

L is a bounded linear map defined on an appropriate space, and  $f:R\to X$  is a locally p-integrable and  $2\pi$ -periodic function for  $1\leq p\prec +\infty$ 

we assume that  $A:D(A)\subseteq X\to X$  and  $B\subseteq X\to X$  are closed linear operator

We denote

$$H^{1,p}(T\,;\mathbf{X})=\{u\in L^p(T\,;X)\,:\ni v\in L^p(T;X), \hat{v}(k)=ik\hat{u}(k)forallk\in Z\}$$

### 2. Preliminaries:

We denote by T the group defined as the quotient  $R/2\pi Z$ . There is an obvious identification between functions on T and  $2\pi$ -periodic functions on R. We consider the interval  $[0,2\pi)$  as a model for T.

For a function  $f \in L^1(T; X)$ , we denote by  $\hat{f}(k)$ ,  $k \in Z$  the k-th Fourier coefficient of f:

$$\hat{f}(\mathbf{k}) = \frac{1}{2\pi} \int_0^1 e^{-ikt} \mathbf{f}(\mathbf{t}) d\mathbf{t}$$
 for  $\mathbf{k} \in \mathbf{Z}$  and  $\mathbf{t} \in \mathbf{R}$ .

Denote  $f_{\tau}(t) := f(t+\tau), \ \tau \in \mathbb{Z}$ ; then it the follows from the definition that  $\hat{f}_{\tau}(\mathbf{k}) = e^{ik\tau} \hat{f}(\mathbf{k}), \ \tau \in \mathbb{T}$ .

Let  $f \in L^p(T,X)$ . Then by Fefer's theorem, one has

$$f = \lim_{n \to \infty} \sigma_n(f)$$

in  $L^p(T,X)$  where

$$\sigma_n(\mathbf{f}) := \frac{1}{n+1} \sum_{m=0}^{n} \sum_{k=-m}^{m} e_k \hat{f}(\mathbf{k})$$

with 
$$e_k(t) := e^{ikt}$$

A Banach space X is said to be UMD, if the Hilbert transform is bounded on  $L^p(R,X)$  for all  $p \in (1,\infty)$ .

Definition 1: Let X and Y be a Banach spaces. A family of operators  $T \subset B(X,Y)$  is called R-bounded, if there is a constant  $C \succ 0$  and  $p \in [1,\infty)$  such that for each  $N \in N, T_j \in T$ ,  $x_j \in X$  and for all independent, symmetric,  $\{-1,1\}$ -valued random variables  $r_j$  on a probability space  $(\Omega, M, \mu)$  the inequality  $\left\|\sum_{j=1}^{N} r_j T_j x_j\right\|_{L^p(\Omega,Y)} \le C \left\|\sum_{j=1}^{N} r_j x_j\right\|_{L^p(\Omega,Y)}$  is valid. The smallest such C is called R-bounded of T, we denot it by  $R_p(T)$ .

Definition 2: For  $1 \le p \infty$  we say that a sequence  $\{M_k\}_{k \in \mathbb{Z}} \subset B(X,Y)$  is an  $L^p$ -multiplier if, for each  $f \in L^p(T,X)$ , there exists  $u \in L^p(T,Y)$  such that  $\hat{u}(k) = M_k \hat{f}(k)$  for all  $k \in \mathbb{Z}$ .

Theorem 1 :[3, theorem 1.3]

Let X, Y be UMD space and let  $\{M_k\}_{k\in Z} \subset B(X,Y)$ . If the sets  $\{M_k\}_{k\in Z}$  and  $\{k(M_{k+1}-M_k)\}_{k\in Z}$  are R-bounded, then  $\{M_k\}_{k\in Z}$  is an  $L^p$ -multiplier for  $1 \prec p \prec \infty$ .

## 3. A Criterion for Periodic Solutions:

We consider:  $\Delta_k = ikI - ikB_k - A(I-B_k) - L_k$ , for all  $k \in \mathbb{Z}$ .

Denote by  $B_k := e^{-ikr} B$ ;  $L_k(x) := L(e^{ik\theta}x)$  and  $e_k(t) := e^{ikt}$  for all  $k \in \mathbb{Z}$  and  $\sigma_Z(\Delta) = \{k \in \mathbb{Z} : \Delta_k \text{ has no inverse}\}$ 

And we define :  $D_k = (ikI - A(I - B_k) - L_k)^{-1}$ 

3.1. Existence of Strong Solution:

Definition 3 Let A be a closed linear operator on X. A function x(.) solution of the problem (1) if  $x \in H^{1,p}(T;X) \cap L^p(T;X)$  and (1) holds for almost all  $t \in [0,2\pi]$ 

Theorem 2: Let X be a Banach space and  $1 \prec p \prec + \infty$ . Suppose that for every  $f \in L^p(T,X)$  there exists a unique strong solution of Eq. (1). Then

- 1. for every  $k \in \mathbb{Z}$  the operator ( ikI-A(I- $B_k)$ - $L_k$ ) has bounded inverse
- 2. The set is R-bounded and  $\{ikD_k\}_{k\in\mathbb{Z}}$  is R-bounded.

Lemma 1 :[2, Lemma 4.2]

Let  $u \in C(T,X)$ . Then

$$\hat{L(X_s(k))} = \hat{L_k}\hat{x}(k).$$

proof of theorem 2:

Let k∈Z, y∈X

for f(t) = 
$$e^{ikr}$$
 y ,  $\exists x \in H^{1,p}(T,X)$  such that :

$$\frac{dx}{dt}(t) = A(x(t)-Bx(t-r)) + L(x_t) + f(t)$$

Taking fourier transform, L is linear and bounded, we obtain

$$ik\hat{x}(k) = A(I-B_k)\hat{x}(k) + L_k\hat{x}(k) + \hat{f}(k)$$

(ikI-A(I-
$$B_k$$
)- $L_k$ ) $\hat{x}(\mathbf{k}) = \hat{f}(\mathbf{k}) = \mathbf{y} \Rightarrow$ ) (ikI-A(I- $B_k$ )- $L_k$ ) is surjective.

Let  $x \in \text{Ker}((ik - A(I-B_k)-L_k))$ , that is  $A(I-B_k)x + L_kx = ikx$ , then  $u(t)=e_kx$  defines a periodic solution of (1) corresponding to the function f(t)=0. Consequently, u(t)=0 and x=0.

2) let  $f \in L^p(T,X)$ . By hypothesis, there exists a unique  $x \in H^{1,p}(T,X)$  such that (1) equation is valid. Taking

Fourier transforms, we deduce that (ikI-A(I- $B_k$ )- $L_k$ ) $\hat{x}(\mathbf{k})=\hat{f}(\mathbf{k})$  for all

 $k \in Z$ . Hence

$$ik\hat{x}(k) = ik (ikI - A(I - B_k) - L_k)^{-1} \hat{f}(k)$$
 for all  $k \in \mathbb{Z}$ 

On the other hand, since  $x \in H^{1,p}(T,X)$ , there exists  $v \in L^p(T,X)$  such that

 $\hat{v}(k)=ik\hat{x}(k)$ . This proves claim.

#### 3.2. Existence of weak solution:

Definition 4: Let A be a closed linear operator on X. A function x(.) is called a weak solution of the problem (1) if  $: \int_0^t (x(s)-Bx(s-r))ds \in D(A)$  and  $x(t) - x(0) = A \int_0^t (x(s)-Bx(s-r))ds + \int_0^t (Lx_s + f(s))ds, \quad 0 \le t \le 2\pi$ .

Theorem 3: Let  $f \in L^p(T,X)$ , Assume that  $\overline{D(A)} = X$ ; if x(.) is said to be a weak solution of Eq (1) then (ikI -A(I-B\_k)-  $L_k$ ) $\hat{x}(k) = \hat{f}(k)$  for all  $k \in \mathbb{Z}$  proof: x(.) is a weak solution of Eq (1) then

$$\mathbf{x}(\mathbf{t}) - \mathbf{x}(0) = \mathbf{A} \int_0^t \mathbf{D} \mathbf{x}(\mathbf{s}) d\mathbf{s} + \int_0^t (\mathbf{G} x_s + \mathbf{f}(\mathbf{s})) d\mathbf{s}$$

$$t = 2\pi$$

 $x(2\pi) - x(0) = A \int_0^{2\pi} (x(s) - Bx(s-r)) ds + \int_0^{2\pi} (Lx_s + f(s)) ds$ ; or  $x(2\pi) = x(0)$  then

$$A \int_0^{2\pi} (x(s)-Bx(s-r))ds + \int_0^{2\pi} (Lx_s + f(s))ds = 0$$

$$(AI - B_0 + L_0)\hat{x}(0) + \hat{f}(0) = 0$$

(0-AI – B<sub>0</sub>- L<sub>0</sub>) $\hat{x}(0) = \hat{f}(0)$  which shows that the assertion holds for k = 0.

Define 
$$v(t) = \int_0^t (x(s)-Bx(s-r))ds$$

And 
$$g(t) = x(t) - x(0) - \int_0^t (Lx_s + f(s))ds$$

by lemma 3.1 [2]

We have  $\hat{v}(k) = \frac{i}{k}(\hat{x}(0) - B\hat{x}(0)) - \frac{i}{k}(\hat{x}(k) - B\hat{x}(k))$  (remark 2.3 [2])

$$\hat{g}(\mathbf{k}) = \hat{x}(\mathbf{k}) - \left[\frac{i}{k}L_0\hat{x}(0) - \frac{i}{k}L_k\hat{x}(\mathbf{k})\right] - \left[\frac{i}{k}\hat{f}(0) - \frac{i}{k}\hat{f}(\mathbf{k})\right]$$

$$\hat{g}(\mathbf{k}) = \hat{x}(\mathbf{k}) - \frac{i}{k} L_0 \hat{x}(0) + \frac{i}{k} L_k \hat{x}(\mathbf{k}) - \frac{i}{k} \hat{f}(0) + \frac{i}{k} \hat{f}(\mathbf{k})$$

$$A\hat{v}(\mathbf{k}) = \frac{i}{k} A(\mathbf{I} - B_0)\hat{x}(0) - \frac{i}{k} A(\mathbf{I} - B_k \hat{x}(\mathbf{k}))$$

Then

$$ik\hat{x}(k) + L_{0}\hat{x}(0) - L_{k}\hat{x}(k) + \hat{f}(0) - \hat{f}(k) = -A(I-B_{0})\hat{x}(0) + A(I-B_{k})\hat{x}(k)$$

$$\Leftrightarrow [ik\hat{x}(k) - A(I-B_{k})\hat{x}(k) - L_{k}\hat{x}(k) - \hat{f}(k)] - [A(I-B_{0})\hat{x}(0) + L_{0}\hat{x}(0) + \hat{f}(0)] = 0$$

$$\Leftrightarrow ik\hat{x}(k) - A(I-B_{k})\hat{x}(k) - L_{k}\hat{x}(k) - \hat{f}(k) = 0$$

$$\Leftrightarrow ik\hat{x}(k) - A(I-B_{k})\hat{x}(k) - L_{k}\hat{x}(k) = \hat{f}(k).$$

Theorem 4 Let  $f \in L^p(T,X)$ , Assume that  $\overline{D(A)} = X$ ; if x(.) is said to be a weak solution of Eq (2) and  $(ikD_k - AD_k - G_k)$  has a bounded inverse. Then  $(ikI - A(I - B_k) - L_k)^{-1}$  is an  $L^p$ -multiplier.

proof; from theorem (1) we have  $\hat{x}(k) = (ikI - A(I - B_k) - L_k)^{-1}\hat{f}(k)$ , for all  $f \in L^p(T,X)$ 

# Main result:

Our main result in this paper, establish that the converse of theorem (2) and the give the definition of Mild solution

#### Theorem 5:

Let X be a UMD space and let A :  $D(A) \subset X \to X$  be a closed linear operator. The following assertions are equivalent for  $1 \prec p \prec \infty$ .

- 1. for every  $f \in L^p(T,X)$  there exists a unique strong solution of Eq (1)
- for every k ∈ Z the operator (ikI-A(I-B<sub>k</sub>)-L<sub>k</sub>) has bounded inverse and the set is R-bounded and {ikD<sub>k</sub>}<sub>k∈Z</sub> is R-bounded.

proof:

 $1 \Leftarrow 2$ ) Let  $f \in L^p(T,X)$ . Define  $D_k = (ikI - A(I - B_k) - L_k)^{-1}$ , the family  $\{ikD_k\}_{k \in \mathbb{Z}}$  is an  $L^p$ -multiplier it is equivalent to the family  $\{D_k\}_{k \in \mathbb{Z}}$  is an  $L^p$ -multiplier that maps  $L^p(T,X)$  into  $H^{1,p}(T,X)$ , [i.e. there exists  $x \in H^{1,p}(T,x)$  such that

$$\hat{x}(k) = D_k \hat{f}(k) = (ikI - A(I - B_k) - L_k)^{-1} \hat{f}(k)$$

In particular,  $x \in L^p(T,X)$  and there exists  $v \in L^p(T,X)$  such that

(1.2) 
$$\hat{x}'(k) := \hat{v}(k) = ik \hat{x}(k)$$

By Fejer's theorem one has in  $L^p([-r_{2\pi},0],X)$ 

$$x_t(\theta) = \mathbf{x}(\mathbf{t} + \theta) = \lim_{n \to +\infty} \frac{1}{n+1} \sum_{m=0}^n \sum_{k=-m}^m e^{ikt} e^{ik\theta} \hat{x}(\mathbf{k})$$

Hence in  $L^p(T,X)$  we obtain

$$x_t = \lim_{n \to +\infty} \frac{1}{n+1} \sum_{m=0}^n \sum_{k=-m}^m e^{ikt} e_k \hat{x}(\mathbf{k})$$

Then, since L is linear and bounded

$$Lx_t = \lim_{n \to +\infty} \frac{1}{n+1} \sum_{m=0}^n \sum_{k=-m}^m e^{ikt} L(e_k \hat{x}(\mathbf{k}))$$
$$= \lim_{n \to +\infty} \frac{1}{n+1} \sum_{m=0}^n \sum_{k=-m}^m e^{ikt} L_k \hat{x}(\mathbf{k})$$

By (1.1) and (1.2) we have

$$\hat{x}'(\mathbf{k}) = i\mathbf{k}\hat{x}(\mathbf{k}) = \mathbf{A}(\mathbf{I} - B_k)\hat{x}(\mathbf{k}) + L_k\hat{x}(\mathbf{k}) + \hat{f}(\mathbf{k}).$$
 for all  $\mathbf{k} \in \mathbf{Z}$ .

Then using that A and B are closed we conclude tat  $(x(t)-Bx(t-r))\in D(A)$ , and from the uniqueness theorem of Fourier coefficients, that equation (2) is valid for  $t \in T$ .[3. lemma 3.1] Definition 5 : of Mild solution about convert of weak solution

Introduction:

Assume that A generates a  $C_0$ -semigroup T(.) on X; and x(.) is a weak solution, then we have

$$\begin{split} & x(t) - x(0) = & A \int_0^t (x(s) - Bx(s-r)) ds + \int_0^t (Gx_s + f(s)) ds \\ & \int_0^t T(t-s) (x(s) - x(0)) ds = \\ & \int_0^t T(t-s) A \int_0^s (x(\xi) - Bx(\xi-r)) d\xi ds + \int_0^t T(t-s) \int_0^s (L(x_\xi) + f(\xi)) d\xi ds \\ & = & \int_0^t (T(t-s) - I) (x(s) - Bx(s-r)) ds + \int_0^t T(t-s) \int_0^s (L(x_\xi) + f(\xi)) d\xi ds \\ & \quad Then \end{split}$$

$$\int_0^t T(t-s)(Bx(s-r)-x(0))ds = -\int_0^s (x(s)-Bx(s-r))ds + \int_0^t T(t-s)\int_0^s (L(x_{\xi}) + f(\xi))d\xi ds$$

$$\int_0^t (\mathbf{x}(\mathbf{s}) - \mathbf{B}\mathbf{x}(\mathbf{s} - \mathbf{r})) \mathrm{d}\mathbf{s} + \int_0^s \mathbf{T}(\mathbf{t} - \mathbf{s}) (\mathbf{B}\mathbf{x}(\mathbf{s} - \mathbf{r}) - \mathbf{x}(0)) \mathrm{d}\mathbf{s} = \int_0^t \mathbf{T}(\mathbf{t} - \mathbf{s}) \int_0^s (\mathbf{L}(x_{\xi}) + \mathbf{f}(\xi)) \mathrm{d}\xi \mathrm{d}\mathbf{s}$$

$$A \int_0^t (\mathbf{x}(\mathbf{s}) - \mathbf{B} \mathbf{x}(\mathbf{s} - \mathbf{r})) d\mathbf{s} + A \int_0^s \mathbf{T}(\mathbf{t} - \mathbf{s}) (\mathbf{B} \mathbf{x}(\mathbf{s} - \mathbf{r}) - \mathbf{x}(0)) d\mathbf{s} = A \int_0^t \mathbf{T}(\mathbf{t} - \mathbf{s}) \int_0^s (\mathbf{L}(x_{\xi}) + \mathbf{f}(\xi)) d\xi d\mathbf{s}$$

$$A \int_0^t (\mathbf{x}(\mathbf{s}) - \mathbf{B} \mathbf{x}(\mathbf{s} - \mathbf{r})) d\mathbf{s} + A \int_0^s \mathbf{T}(\mathbf{t} - \mathbf{s}) (\mathbf{B} \mathbf{x}(\mathbf{s} - \mathbf{r}) - \mathbf{x}(\mathbf{0})) d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) + \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) + \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{f}(\xi)) d\xi d\mathbf{s} = \int_0^t (\mathbf{L}(x_{\xi}) - \mathbf{I}) \int_0^s (\mathbf{L}(x_{\xi}) - \mathbf{I}) d\xi d\mathbf{s} = \int_0^t (\mathbf{L}(x_{\xi}) - \mathbf{I}) d\mathbf{s} = \int_0^t (\mathbf{L}(x_{\xi}) - \mathbf{I}) d\mathbf{s} d\mathbf{s} d\mathbf{s} = \int_0^t (\mathbf{L}(x_{\xi}) - \mathbf{I}) d\mathbf{s} d\mathbf{s} d\mathbf{s} = \int_0^t (\mathbf{L}(x_{\xi}) - \mathbf{I}) d\mathbf{s} d\mathbf{s} d\mathbf{s} d\mathbf{s} = \int_0^t (\mathbf{L}(x_{\xi}) - \mathbf{I}) d\mathbf{s} d\mathbf{s} d\mathbf{s} d\mathbf{s} d\mathbf{s} d\mathbf{s} d\mathbf{s} d\mathbf{s} = \int_0^t (\mathbf{L}(x_{\xi}) - \mathbf{I}) d\mathbf{s} d\mathbf$$

$$\begin{array}{l} A \int_0^t (x(s)-Bx(s-r)) ds + \int_0^t (L(x_s)+f(s)) ds = \\ \int_0^t T(t-s)(L(x_s)+f(s)) ds + A \int_0^t T(t-s)(x(0)-Bx(s-r)) ds \end{array}$$

or x(.) is a weak solution then

$$x(t) - x(0) = A \int_0^t T(t-s)(x(0)-Bx(s-r))ds + \int_0^t T(t-s)(L(x_s)+f(s))ds$$

Our object, establish the convese of this result

Definition 6 : Assume that A generates a  $C_0$ -semigroup T(.) on X. A func-

tion x(.) is called a mild solution of the problem (1) if:

$$\int_0^t T(t-s)(x(0)-Bx(s-r))ds \in D(A)$$
 and

$$x(t) - x(0) = A \int_0^t T(t-s) \big( x(0) - Bx(s-r) \big) ds \ + \ \int_0^t T(t-s) \big( L(x_s) + f(s) \big) ds \ \ 0 \le t \le 2\pi.$$

Corollary 1 Assume that A generates a  $C_0$ -semigroup T(.) on X; let  $f \in L^p(T,X)$ 

x(.) is a weak solution  $\Leftrightarrow x(.)$  is a mild solution proof:

- ⇒) by introduction
- ←) suppose that x(.) is a mild solution of Eq (2) then

$$x(t) - x(0) = A \int_0^t T(t-s)(x(0)-Bx(s-r))ds + \int_0^t T(t-s)(L(x_s)+f(s))ds$$

$$\begin{split} &\int_0^t (\mathbf{x}(\mathbf{s}) - \mathbf{x}(0)) \mathrm{d}\mathbf{s} = \int_0^t \mathbf{A} \int_0^s \mathbf{T}(\mathbf{t} - \xi) (\mathbf{x}(0) - \mathbf{B}\mathbf{x}(\xi - \mathbf{r})) \mathrm{d}\xi \mathrm{d}\mathbf{s} + \int_0^t \int_0^s \mathbf{T}(\mathbf{t} - \xi) (\mathbf{L}(x_\xi) + \mathbf{f}(\xi)) \mathrm{d}\xi \mathrm{d}\mathbf{s} \\ &\int_0^t (\mathbf{x}(\mathbf{s}) - \mathbf{x}(0)) \mathrm{d}\mathbf{s} = \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) (\mathbf{x}(0) - \mathbf{B}\mathbf{x}(\mathbf{s} - \mathbf{r})) \mathrm{d}\mathbf{s} + \int_0^t \int_0^s \mathbf{T}(\mathbf{t} - \xi) (\mathbf{L}(x_\xi) + \mathbf{f}(\xi)) \mathrm{d}\xi \mathrm{d}\mathbf{s} \\ &A \int_0^t (\mathbf{x}(\mathbf{s}) - \mathbf{x}(0)) \mathrm{d}\mathbf{s} = A \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) (\mathbf{x}(0) - \mathbf{B}\mathbf{x}(\mathbf{s} - \mathbf{r})) \mathrm{d}\mathbf{s} + A \int_0^t \int_0^s \mathbf{T}(\mathbf{t} - \xi) (\mathbf{L}(x_\xi) + \mathbf{f}(\xi)) \mathrm{d}\xi \mathrm{d}\mathbf{s} \\ &A \int_0^t (\mathbf{x}(\mathbf{s}) - \mathbf{x}(0)) \mathrm{d}\mathbf{s} = A \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) (\mathbf{x}(0) - \mathbf{B}\mathbf{x}(\mathbf{s} - \mathbf{r})) \mathrm{d}\mathbf{s} + \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) (\mathbf{L}(x_\xi) + \mathbf{f}(\xi)) \mathrm{d}\mathbf{s} \\ &A \int_0^t (\mathbf{x}(\mathbf{s}) - \mathbf{x}(0)) \mathrm{d}\mathbf{s} = A \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) (\mathbf{x}(0) - \mathbf{B}\mathbf{x}(\mathbf{s} - \mathbf{r})) \mathrm{d}\mathbf{s} + \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) (\mathbf{L}(x_\xi) + \mathbf{f}(\xi)) \mathrm{d}\mathbf{s} \\ &A \int_0^t (\mathbf{x}(\mathbf{s}) - \mathbf{x}(0)) \mathrm{d}\mathbf{s} = A \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) (\mathbf{x}(0) - \mathbf{B}\mathbf{x}(\mathbf{s} - \mathbf{r})) \mathrm{d}\mathbf{s} + \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) (\mathbf{L}(x_\xi) + \mathbf{f}(\xi)) \mathrm{d}\mathbf{s} \\ &A \int_0^t (\mathbf{x}(\mathbf{s}) - \mathbf{x}(0)) \mathrm{d}\mathbf{s} = A \int_0^t (\mathbf{T}(\mathbf{t} - \mathbf{s}) - \mathbf{I}) (\mathbf{x}(0) - \mathbf{B}\mathbf{x}(\mathbf{s} - \mathbf{r})) \mathrm{d}\mathbf{s} \\ &A \int_0^t (\mathbf{x}(\mathbf{s}) - \mathbf{x}(0)) \mathrm{d}\mathbf{s} \\ &A \int_0^t (\mathbf{x}($$

$$\begin{array}{l} {\bf A} \int_0^t ({\bf x}({\bf s}) - {\bf x}(0)) {\rm d}{\bf s} + \int_0^t ({\bf L}(x_s) + {\bf f}({\bf s})) {\rm d}{\bf s} + {\bf A} \int_0^t ({\bf x}(0) - {\bf B}{\bf x}({\bf s} - {\bf r})) {\rm d}{\bf s} = {\bf A} \int_0^t {\bf T}({\bf t} - {\bf s}) ({\bf x}(0) - {\bf B}{\bf x}({\bf s} - {\bf r})) {\rm d}{\bf s} + \int_0^t ({\bf T}({\bf t} - {\bf s}) ({\bf L}(x_s) + {\bf f}({\bf s})) {\rm d}{\bf s} \\ \end{array}$$

$$\underbrace{A\int_{0}^{t} T(t-s)(x(0)-Bx(s-r))ds + \int_{0}^{t} (T(t-s)(L(x_{s})+f(s))ds = A\int_{0}^{t} (x(s)-x(t)-x(0))ds + \int_{0}^{t} T(t-s)(x(0)-Bx(s-r))ds + \int_{0}^{t} T(t-s)(L(x_{s})+f(s))ds = A\int_{0}^{t} (x(s)-x(t)-x(t))ds = A\int_{0}^{t} (x(s)-x(t))ds = A\int_{0}^$$

$$Bx(s-r)ds + \int_0^t (L(x_s) + f(s))ds$$

x(t)-x(0) =  $A \int_0^t (x(s)-Bx(s-r))ds + \int_0^t (L(x_s)+f(s))ds$  then x(.) is a weak solution.

Proposition 1: Assume that A generates a  $C_0$ -semigroup T(.) on X. if  $(ikI - A(I - B_k) - L_k)^{-1}$  is an  $L^p$ -multiplier Then there exists a unique weak(mild) solution of Eq. (1).

proof : let 
$$f \in L^{p}(T,X)$$
, then  $f(t) = \lim_{n \to +\infty} \frac{1}{n+1} \sum_{m=0}^{n} \sum_{k=-m}^{m} e^{ikt} \hat{f}(k)$  or  $(ikI - A(I - B_k) - L_k)^{-1}$  is an  $L^{p}$ -multiplier then there exists  $x \in L^{p}(T,X)$  such that  $\hat{x}(k) = (ikI - A(I - B_k) - L_k)^{-1} \hat{f}(k)$  put  $x_n(t) = \lim_{n \to +\infty} \frac{1}{n+1} \sum_{n=0}^{n} \sum_{k=-m}^{m} e^{ikt} (ikI - A(I - B_k) - L_k)^{-1} \hat{f}(k)$  then  $x_n(t) \to x(t)$  and  $x_n$  is strong  $L^{p}$ -solution of Eq. (1) and  $x_n$  verified  $x_n(t) - x_n(0) = A \int_0^t ((x_n(t-s)) - Bx_n(t-s)) ds + \int_0^t (G((x_n)_s) + f_n(s)) ds$  we put  $y_n = x_n(0)$  then  $x_n(t) = y_n + A \int_0^t ((x_n(t-s)) - Bx_n(t-s)) ds + \int_0^t (L((x_n)_s) + f_n(s)) ds$  then  $x_n(t) = y_n + A \int_0^{2\pi} ((x_n(t-s)) - Bx_n(2\pi-s)) ds + \int_0^{2\pi} (L((x_n)_s) + f_n(s)) ds$  then  $x_n(t) = y_n + A \int_0^{2\pi} ((x_n(t-s)) - Bx_n(2\pi-s)) ds + \int_0^{2\pi} (L((x_n)_s) + f_n(s)) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} ((x_n(t-s)) - Bx_n(2\pi-s)) ds + \int_0^{2\pi} (L((x_n)_s) + f_n(s)) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} ((x_n(t-s)) - Bx_n(2\pi-s)) ds + \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} ((x_n(t-s)) - Bx_n(2\pi-s)) ds + \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} ((x_n(t-s)) - Bx_n(2\pi-s)) ds + \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} ((x_n(t-s)) - Bx_n(2\pi-s)) ds + \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} ((x_n(t-s)) - Bx_n(2\pi-s)) ds + \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} ((x_n(t-s)) - Bx_n(2\pi-s)) ds + \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} ((x_n(t-s)) - Bx_n(2\pi-s)) ds + \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} (L(x_n)_s) + f_n(s) ds$  and  $x_n(t) = y_n + A \int_0^{2\pi} (L(x_n)_s) +$ 

$$\frac{d}{dt}x(t) = A(x(t) - Bx(t-r)) + Lx_t + f(t)$$

let A be a closed linear operator and X be a UMD space, and

 $\sup_{k} \|(ikI - A(I - B_k))^{-1}\| = : M \prec \infty \text{ and } \|L\| \prec \frac{1}{r_{2\pi}^{1/p}} \text{then Eq (1) has a unique weak solution.}$  we have  $ikI - A(I - B_k) - L_k = [ikI - A(I - B_k)][I - L_k(ikI - A(I - B_k))^{-1}]$  it follows that  $ikI - A(I - B_k) - L_k$  is invertible whenever  $\|L_k(ikI - A(I - B_k))^{-1}\| \prec 1$  [7. Theorem 1.1.7] observe that  $\|L_k\| \le r_{2\pi}^{1/p}\|L\|$  Hence  $\|L_k(ikI - A(I - B_k))^{-1}\| \le r_{2\pi}^{1/p}\|L\|M := \alpha$  Therefore, under the condition  $\|L\| \prec \frac{1}{r_{2\pi}^{1/p}M}$   $(ikI - A(I - B_k) - L_k)^{-1} = [ikI - A(B_k)]^{-1}[I - L_k(ikI - A(I - B_k)^{-1}]^{-1}$   $= [ikI - A(B_k)]^{-1}\sum_{n=0}^{\infty} [L_k(ikI - A(I - B_k)^{-1}]^n$  it follows that :  $\|ik(ikI - A(I - B_k) - L_k)^{-1}\| \le \|ik(ikI - A(I - B_k))^{-1}\|\sum_{n=0}^{\infty} \alpha^n$   $\le \frac{M+1}{1-\alpha}$  then  $ikD_k$  is R-bounded.

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