

On RAM Finite Hyperbolic Transforms

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Abstract: In this paper we have introduced the new concept of RAM finite hyperbolic transforms. Transform of some standard functions are obtained and some properties are proved.

Keywords: Generalized Transform, Finite transform, RAM Finite hyperbolic transform, Transform of some standard functions.

I. Introduction:

The Laplace transform method is normally used to find the response of a linear system at any time t to the initial data at $t = 0$ and disturbance $f(t)$ acting for $t > 0$. If the disturbance is $f(t) = e^{at^2}$, for $a > 0$, the usual Laplace transform cannot be used to find the solution of an initial value problem because Laplace transform of $f(t)$ does not exist. It is often true that the solution at times later than t would not affect the state at time t . This leads to define Finite Laplace transform.

The finite Laplace transform of a continuous or an almost piecewise continuous function $f(t)$ in $(0, T)$ is denoted by $L_T(f(t)) = F(p, T)$, and is defined by

$$L_T(f(t)) = F(p, T) = \int_0^T f(t)e^{-pt} dt \quad (1.1)$$

Where p is a real or complex number and T be a finite number which may be positive or negative.

Note : Above definition is defined for any bounded interval $(-T_1, T_2)$.

Finite Laplace transform motivate us to define RAM Finite Sine Hyperbolic transform and RAM Finite Cosine Hyperbolic transform in $0 \leq t \leq T$ in order to extend the power and usefulness of usual Laplace transform in $0 \leq t < \infty$. In section 2, the concept of RAM Finite Hyperbolic Transforms is introduced. Section 3 is devoted to explain existence conditions for these transforms. Sections 4 and 5 are devoted to obtain these transforms of some standard functions. Some properties like Linearity, Scalar Multiplication, and Scaling are proved in sections 6 and 7. Section 8 is devoted to Discussion and Conclusion.

II. RAM Finite Hyperbolic Transforms:

Definition 2.1: Let $p \in C$ and T be a finite number which may be positive or negative and $f(t)$ is a continuous or an almost piecewise continuous function defined over the interval $(0, T)$. Then RAM Finite Sine Hyperbolic transform of $f(t)$ is denoted by $R_{sh}(f(t)) = F_s(p, T)$, and defined by

$$R_{sh}(f(t)) = F_s(p, T) = \int_0^T \sinh(pt)f(t)dt,$$

where $\sinh(pt)$ is a Kernel of R_{sh} .

Here R_{sh} is called RAM Finite Sine Hyperbolic transformation operator.

Definition 2.2: Let $p \in C$ and T be a finite number which may be positive or negative and $f(t)$ is a continuous or an almost piecewise continuous function defined over the interval $(0, T)$. Then RAM Finite Cosine Hyperbolic transform of $f(t)$ is denoted by $R_{ch}(f(t)) = F_c(p, T)$, and defined by

$$R_{ch}(f(t)) = F_c(p, T) = \int_0^T \cosh(pt)f(t)dt,$$

where $\cosh(pt)$ is a Kernel of R_{ch} .

Here R_{ch} is called RAM Finite Cosine Hyperbolic transformation operator.

Note : \sinh , \cosh are bounded for any bounded interval $(-T_1, T_2)$.

III. Existence of R_{sh} and R_{ch} .

Theorem 3.1 If $f(t)$ is a piecewise continuous and absolutely integrable function on $(0, T)$, then $R_{sh}(f(t))$ exists.

Proof: As \sinh is bounded on $(0, T)$, there exist $K \in [0, \infty)$ such that $|\sinh(pt)| \leq K$ on $(0, T)$. Since $f(t)$ is

absolutely integrable, there exist $M \in [0, \infty)$ such that $\int_0^T |f(t)| dt \leq M$.

Consider

$$\begin{aligned}
 |R_{sh}(f(t))| &= \left| \int_0^T \sinh(pt) f(t) dt \right| \\
 &\leq \int_0^T |\sinh(pt)| |f(t)| dt \\
 &\leq \int_0^T K |f(t)| dt \\
 &\leq K \int_0^T |f(t)| dt \\
 \Rightarrow |R_{sh}(f(t))| &\leq K.M.
 \end{aligned}$$

Thus $R_{sh}(f(t))$ exists. Hence proved.

Theorem 3.2: If $f(t)$ is a piecewise continuous and absolutely integrable function on $(0, T)$, then $R_{ch}(f(t))$ exists.

Proof: Consider

$$\begin{aligned}
 |R_{ch}(f(t))| &= \left| \int_0^T \cosh(pt) f(t) dt \right| \\
 &\leq \int_0^T |\cosh(pt)| |f(t)| dt \\
 &\leq \int_0^T K |f(t)| dt \quad (\text{since } |\cosh(pt)| \leq K \text{ on } (0, T), 0 \leq K < \infty) \\
 &\leq K \int_0^T |f(t)| dt \\
 \Rightarrow |R_{ch}(f(t))| &\leq M.K. \quad (\text{since } \int_0^T |f(t)| dt \leq M, 0 \leq M < \infty)
 \end{aligned}$$

Thus $R_{ch}(f(t))$ exists. Hence proved.

Theorem 3.3: If $f(t)$ is a piecewise continuous and bounded function on $(0, T)$, then

$$R_{sh}(f(t)) \text{ exists.}$$

Proof: Consider

$$\begin{aligned}
 |R_{sh}(f(t))| &= \left| \int_0^T \sinh(pt) f(t) dt \right| \\
 &\leq \int_0^T |\sinh(pt)| |f(t)| dt \\
 &\leq \int_0^T M.K. |f(t)| dt \quad (\text{since } |f(t)| \leq M \text{ on } (0, T), 0 \leq K, M < \infty) \\
 \Rightarrow |R_{sh}(f(t))| &\leq M.K.T.
 \end{aligned}$$

Thus R_{sh} exists. Hence proved.

Theorem 3.4: If $f(t)$ is a piecewise continuous and bounded function on $(0, T)$, then $R_{ch}(f(t))$ exists.

Proof : consider

$$\begin{aligned}
 |R_{sh}(f(t))| &= \left| \int_0^T \cosh(pt) f(t) dt \right| \\
 &\leq \int_0^T |\cosh(pt)| |f(t)| dt \\
 &\leq MK \int_0^T |f(t)| dt \quad (\text{since } |\cosh(pt)| \leq K, |f(t)| \leq M \text{ on } (0, T), 0 \leq K, M < \infty) \\
 \Rightarrow |R_{ch}(f(t))| &\leq M.K.T.
 \end{aligned}$$

Thus $R_{ch}(f(t))$ exists. Hence Proved.

IV. RAM Finite Sine Hyperbolic transform of some standard functions:

$$1. \quad R_{sh}(1) = \frac{\cosh(pT) - 1}{p}$$

Proof:

$$\begin{aligned} R_{sh}(1) &= \int_0^T \sinh(pt) dt \\ &= \frac{\cosh(pt) - 1}{p} \end{aligned}$$

$$2. \quad R_{sh}(t) = \frac{T \cosh(pt)}{p} - \frac{\sinh(pt)}{p^2}$$

Proof:

$$\begin{aligned} R_{sh}(t) &= \int_0^T t \sinh(pt) dt \\ &= \frac{T \cosh(pt)}{p} - \frac{\sinh(pt)}{p^2} \end{aligned}$$

$$3. \quad R_{sh}(t^2) = \frac{T^2 \cosh(pt)}{p} - \frac{2T \sinh(pt)}{p^2} + \frac{(2 \cosh(pt) - 2)}{p^3}.$$

Proof:

$$\begin{aligned} R_{sh}(t^2) &= \int_0^T t^2 \sinh(pt) dt \\ &= \frac{T^2 \cosh(pt)}{p} - \frac{2T \sinh(pt)}{p^2} + \frac{(2 \cosh(pt) - 2)}{p^3}. \end{aligned}$$

$$4. \quad R_{sh}(t^k) = \begin{cases} \frac{T^k \cosh(pt)}{p} - \frac{k T^{k-1} \sinh(pt)}{P^2} + \dots + \frac{k!(-1)^k [\cosh(pt) - 1]}{p^k}, & \text{if } k \text{ is even} \\ \frac{T^k \cosh(pt)}{p} - \frac{k T^{k-1} \sinh(pt)}{P^2} + \dots + \frac{k!(-1)^k \sinh(pt)}{p^k}, & \text{if } k \text{ is odd} \end{cases}$$

Proof:

$$\begin{aligned} R_{sh}(t^k) &= \int_0^T t^k \sinh(pt) dt \\ &= \left[\frac{t^k \cosh(pt)}{p} \right]_0^T - \left[\frac{k t^{k-1} \sinh(pt)}{p^2} \right]_0^T + \dots + \left[\frac{k!(-1)^k \cosh(pt)}{p^k} \right]_0^T, \text{ if } k \text{ is even,} \\ &= \left[\frac{t^k \cosh(pt)}{p} \right]_0^T - \left[\frac{k t^{k-1} \sinh(pt)}{p^2} \right]_0^T + \dots + \left[\frac{k!(-1)^k \sinh(pt)}{p^k} \right]_0^T, \text{ if } k \text{ is odd.} \\ &= \begin{cases} \frac{T^k \cosh(pt)}{p} - \frac{k T^{k-1} \sinh(pt)}{P^2} + \dots + \frac{k!(-1)^k [\cosh(pt) - 1]}{p^k}, & \text{if } k \text{ is even} \\ \frac{T^k \cosh(pt)}{p} - \frac{k T^{k-1} \sinh(pt)}{P^2} + \dots + \frac{k!(-1)^k \sinh(pt)}{p^k}, & \text{if } k \text{ is odd} \end{cases} \\ 5. \quad R_{sh}(\sin(at)) &= \left(\frac{-a}{p^2 + a^2} \right) \sinh(pt) \cos(at) + \left(\frac{p}{p^2 + a^2} \right) \cosh(pt) \sin(at). \end{aligned}$$

Proof:

$$\begin{aligned}
 R_{sh}(\sin(at)) &= \int_0^T \sin(at) \sinh(pt) dt \\
 &= \frac{\sinh(pT)\cos(aT)}{-a} + \frac{p\cos(pT)\sin(aT)}{a^2} - \frac{p^2 R_{sh}(\sin(at))}{a^2}. \\
 \Rightarrow \left(1 + \frac{p^2}{a^2}\right) R_{sh}(\sin(at)) &= \frac{\sinh(pT).\cos(aT)}{-a} + \frac{p.\cos(pT).\sin(aT)}{a^2}.
 \end{aligned}$$

i.e. $R_{sh}(\sin(at)) = \left(\frac{-a}{p^2+a^2}\right) \sinh(pT). \cos(aT) + \left(\frac{p}{p^2+a^2}\right) \cosh(pT) \sin(aT).$

6. $R_{sh}(\cos(at)) = \left(\frac{a}{p^2+a^2}\right) \sinh(pT). \sin(aT) + \left(\frac{p}{p^2+a^2}\right) [\cosh(pT). \cos(aT) - 1].$

Proof:

$$\begin{aligned}
 R_{sh}(\cos(at)) &= \int_0^T \cos(at) \sinh(pt) dt \\
 &= \frac{\sinh(pT).\sin(aT)}{a} + \frac{[p.\cosh(pT).\cos(aT) - p]}{a^2} - \frac{p^2.R_{sh}(\cos(at))}{a^2} \\
 \Rightarrow \left(1 + \frac{p^2}{a^2}\right) R_{sh}(\cos(at)) &= \frac{\sinh(pT)\sin(aT)}{a} + \frac{[p.\cosh(pT).\cos(aT) - p]}{a^2} \\
 \text{i.e. } R_{sh}(\cos(at)) &= \left(\frac{a}{p^2+a^2}\right) \sinh(pT). \sin(aT) + \left(\frac{p}{p^2+a^2}\right) [\cosh(pT). \cos(aT) - 1]. \\
 7. \quad R_{sh}(e^{at}) &= \left(\frac{-a}{p^2-a^2}\right) \sinh(pT). e^{at} + \left(\frac{p}{p^2-a^2}\right) [\cosh(pT). e^{at} - 1], \text{ provided } p^2 \neq a^2.
 \end{aligned}$$

Proof:

$$\begin{aligned}
 R_{sh}(e^{at}) &= \int_0^T e^{at} \sinh(pt) dt \\
 &= \frac{\sinh(pT).e^{at}}{a} - \frac{[p.\cos(pT)e^{at} - p]}{a^2} + \frac{p^2.R_{sh}(e^{at})}{a^2} \\
 \Rightarrow R_{sh}(e^{at}) &= \left(\frac{-a}{p^2-a^2}\right) \sinh(pT). e^{at} + \left(\frac{p}{p^2-a^2}\right) [\cosh(pT). e^{at} - 1], \text{ provided } p^2 \neq a^2. \\
 8. \quad R_{sh}(e^{-at}) &= \left(\frac{a}{p^2-a^2}\right) \sinh(pT). e^{-at} + \left(\frac{-p}{p^2-a^2}\right) [1-\cosh(pT). e^{-at}], \text{ Provided } P^2 \neq a^2.
 \end{aligned}$$

Proof:

$$\begin{aligned}
 R_{sh}(e^{-at}) &= \int_0^T e^{-at} \sinh(pt) dt \\
 &= \frac{\sinh(pT).e^{-at}}{-a} - \frac{[p.\cosh(pT).e^{-at} - p]}{a^2} + \frac{p^2.R_{sh}(e^{-at})}{a^2} \\
 \Rightarrow \left(1 - \frac{p^2}{a^2}\right) R_{sh}(e^{-at}) &= \frac{\sinh(pT).e^{-at}}{-a} - \frac{[p.\cosh(pT).e^{-at} - p]}{a^2} \\
 \text{i.e. } R_{sh}(e^{-at}) &= \left(\frac{a}{p^2-a^2}\right) \sinh(pT). e^{-at} + \left(\frac{-p}{p^2-a^2}\right) [1-\cosh(pT). e^{-at}], \text{ provided } p^2 \neq a^2.
 \end{aligned}$$

V. RAM Finite Cosine Hyperbolic Transform of some standard functions:

$$1. \quad R_{ch}(1) = \frac{\sinh(pT)}{p}.$$

Proof:

$$\begin{aligned} R_{ch}(t) &= \int_0^T \cosh(pt) dt \\ &= \frac{\sinh(pT)}{p} \end{aligned}$$

$$2. \quad R_{ch}(t) = \frac{T\sinh(pT)}{p} - \left(\frac{\cosh(pT)-1}{p^2} \right)$$

Proof:

$$\begin{aligned} R_{ch}(t) &= \int_0^T t \cosh(pt) dt \\ &= \frac{T\sinh(pT)}{p} - \left(\frac{\cosh(pT)-1}{p^2} \right) \end{aligned}$$

$$3. \quad R_{ch}(t^2) = \frac{T^2 \cdot \sinh(pT)}{p} - \frac{2 \cdot T \cdot \cosh(pT)}{P^2} + \frac{2 \cdot \sinh(pT)}{p^3}.$$

Proof:

$$\begin{aligned} R_{ch}(t) &= \int_0^T t^2 \cdot \cosh(pt) dt \\ &= \frac{T^2 \cdot \sinh(pT)}{p} - \frac{2 \cdot T \cdot \cosh(pT)}{P^2} + \frac{2 \cdot \sinh(pT)}{p^3}. \\ 4. \quad R_{ch}(t^k) &= \begin{cases} \frac{T^k \sinh(pT)}{p} - \frac{kT^{k-1} \cosh(pT)}{p^2} + \dots + \frac{k!(-1)^k \sinh(pT)}{p^k}, & \text{if } k \text{ is even,} \\ \frac{T^k \sinh(pT)}{p} - \frac{kT^{k-1} \cosh(pT)}{p^2} + \dots + \frac{k!(-1)^k [\cosh(pT)-1]}{p^k}, & \text{if } k \text{ is odd.} \end{cases} \end{aligned}$$

Proof:

$$\begin{aligned} R_{ch}(t^k) &= \int_0^T t^k \cosh(pt) dt \\ &= \left[\frac{t^k \sinh(pt)}{p} \right]_0^T - \left[\frac{kt^{k-1} \cosh(pt)}{P^2} \right]_0^T + \dots + \left[\frac{k!(-1)^k \sinh(pt)}{p^k} \right]_0^T, \text{ if } k \text{ is even} \\ &= \left[\frac{t^k \cdot \sinh(pt)}{p} \right]_0^T - \left[\frac{kt^{k-1} \cosh(pt)}{P^2} \right]_0^T + \dots + \left[\frac{k!(-1)^k \cosh(pt)}{p^k} \right]_0^T, \text{ if } k \text{ is odd} \\ &= \frac{T^k \sinh(pT)}{p} - \frac{kT^{k-1} \cosh(pT)}{p^2} + \dots + \frac{k!(-1)^k \sinh(pT)}{p^k}, \text{ if } k \text{ is even,} \\ &= \frac{T^k \sinh(pT)}{p} - \frac{kT^{k-1} \cosh(pT)}{p^2} + \dots + \frac{k!(-1)^k [\cosh(pT)-1]}{p^k}, \text{ if } k \text{ is odd.} \end{aligned}$$

$$5. \quad R_{ch}(\sin(at)) = \left(\frac{a}{p^2 + a^2} \right) [1 - \cosh(pT) \cos(aT)] + \left(\frac{p}{p^2 + a^2} \right) \sinh(pT) \sin(aT).$$

Proof:

$$\begin{aligned}
 R_{ch}(\sin(at)) &= \int_0^T \sin(at) \cosh(pt) dt \\
 &= \frac{[\cos(pT)\cos(aT)-1]}{-a} + \frac{p \sinh(pT)\sin(aT)}{a^2} - \frac{p^2 R_{ch}(\sin(at))}{a^2} \\
 \Rightarrow \left(1 + \frac{p^2}{a^2}\right) R_{ch}(\sin(at)) &= \frac{[\cos(pT)\cos(aT)-1]}{-a} + \frac{p \sinh(pT)\sin(aT)}{a^2} \\
 \text{i.e. } R_{ch}(\sin(at)) &= \left(\frac{a}{p^2+a^2}\right) [1 - \cosh(pT) \cos(aT)] + \left(\frac{p}{p^2+a^2}\right) \sinh(pT) \sin(aT). \\
 6. \quad R_{ch}(\cos(at)) &= \left(\frac{a}{p^2+a^2}\right) \cosh(pT) \sin(aT) + \left(\frac{p}{p^2+a^2}\right) \sinh(pT) \cos(aT).
 \end{aligned}$$

Proof:

$$\begin{aligned}
 R_{ch} \cos(at) &= \int_0^T \cos(at) \cosh(pt) dt \\
 &= \frac{\cosh(pT)\sin(aT)}{a} + \frac{p \sinh(pT)\cos(aT)}{a^2} - \frac{p^2 R_{ch}(\cos(at))}{a^2} \\
 \Rightarrow \left(1 + \frac{p^2}{a^2}\right) R_{ch}(\cos(at)) &= \frac{\cosh(pT)\sin(aT)}{a} + \frac{p \sinh(pT)\cos(aT)}{a^2} \\
 \text{i.e. } R_{ch}(\cos(at)) &= \left(\frac{a}{p^2+a^2}\right) \cosh(pT) \sin(aT) + \left(\frac{p}{p^2+a^2}\right) \sinh(pT) \cos(aT). \\
 7. \quad R_{ch}(e^{at}) &= \left(\frac{a}{p^2-a^2}\right) [\cosh(pT) e^{at} - 1] + \left(\frac{p}{p^2-a^2}\right) \sinh(pT) e^{at}, \text{ Provided } p^2 \neq a^2.
 \end{aligned}$$

Proof:

$$\begin{aligned}
 R_{ch}(e^{at}) &= \int_0^T e^{at} \cosh(pt) dt \\
 &= \frac{[\cosh(pT)e^{at}-1]}{a} - \frac{p \sinh(pT)e^{at}}{a^2} + \frac{p^2 R_{ch}(e^{at})}{a^2} \\
 \Rightarrow \left(1 - \frac{p^2}{a^2}\right) R_{ch}(e^{at}) &= \frac{[\cosh(pT)e^{at}-1]}{a} - \frac{p \sinh(pT)e^{at}}{a^2} \\
 \text{i.e. } R_{ch}(e^{at}) &= \left(\frac{a}{p^2-a^2}\right) [\cosh(pT) e^{at} - 1] + \left(\frac{p}{p^2-a^2}\right) \sinh(pT) e^{at}, \text{ Provided } p^2 \neq a^2. \\
 8. \quad R_{ch}(e^{-at}) &= \left(\frac{a}{p^2-a^2}\right) \cosh(pT) e^{-at} + \left(\frac{-p}{p^2-a^2}\right) [1-\sinh(pT) e^{-at}], \text{ provided } p^2 \neq a^2.
 \end{aligned}$$

Proof :

$$\begin{aligned}
 R_{ch}(e^{-at}) &= \int_0^T e^{-at} \cosh(pt) dt \\
 &= \frac{[\cosh(pT)e^{-at}-1]}{-a} - \frac{p \sinh(pT)e^{-at}}{a^2} + \frac{p^2 R_{ch}(e^{-at})}{a^2} \\
 \Rightarrow \left(1 - \frac{p^2}{a^2}\right) R_{ch}(e^{-at}) &= \frac{[\cosh(pT)e^{-at}-1]}{-a} - \frac{p \sinh(pT)e^{-at}}{a^2}
 \end{aligned}$$

$$\text{i.e. } R_{ch}(e^{-at}) = \left(\frac{a}{p^2 - a^2} \right) (\cosh(pt) e^{-at} - 1) + \left(\frac{-p}{p^2 - a^2} \right) [\sinh(pt) e^{-at}] ; \text{ provided } p^2 \neq a^2.$$

VI. Some Properties of RAM Finite Sine Hyperbolic transform:

1. **Linearity:** $R_{sh}(f_1(t) + f_2(t)) = R_{sh}(f_1(t)) + R_{sh}(f_2(t))$.

Proof: Let $0 < t < T$, then by definition

$$\begin{aligned} R_{sh}(f_1(t) + f_2(t)) &= \int_0^T (f_1(t) + f_2(t)) \sinh(pt) dt \\ &= \int_0^T f_1(t) \sinh(pt) dt + \int_0^T f_2(t) \sinh(pt) dt \\ &= R_{sh}(f_1(t)) + R_{sh}(f_2(t)). \end{aligned}$$

2. **Scalar Multiplication:** If c be any constant, then $R_{sh}(cf(t)) = cR_{sh}(f(t))$.

Proof: Let c be any constant, then by definition

$$\begin{aligned} R_{sh}(cf(t)) &= \int_0^T c f(t) \sinh(pt) dt \\ &= c \int_0^T f(t) \sinh(pt) dt \\ &= c R_{sh}(f(t)). \end{aligned}$$

3. **Scaling:** If $R_{sh}(f(t)) = F_s(p, T)$ then $R_{sh}(f(at)) = \frac{F_s\left(\frac{p}{a}, aT\right)}{a}$

Proof: Let $R_{sh}(f(t)) = F_s(p, T)$, then by definition

$$\begin{aligned} R_{sh}(f(at)) &= \int_0^T f(at) \sinh(pt) dt \\ &= \int_0^T \frac{f(x) \sinh\left(\frac{xp}{a}\right)}{a} dx \\ &= \frac{F_s\left(\frac{p}{a}, aT\right)}{a} \end{aligned}$$

VII. Some Properties of RAM Finite Cosine Hyperbolic transform:

1. **Linearity :** $R_{ch}(f_1(t) + f_2(t)) = R_{ch}(f_1(t)) + R_{ch}(f_2(t))$

Proof: Let $0 < t < T$, then by definition

$$\begin{aligned} R_{ch}(f_1(t) + f_2(t)) &= \int_0^T (f_1(t) + f_2(t)) \cosh(pt) dt \\ &= \int_0^T f_1(t) \cosh(pt) dt + \int_0^T f_2(t) \cosh(pt) dt \\ &= R_{ch}(f_1(t)) + R_{ch}(f_2(t)). \end{aligned}$$

2. **Scalar Multiplication:** If c is any constant, then $R_{ch}(c f(t)) = c R_{ch}(f(t))$

Proof: Let c be any constant, then by definition

$$\begin{aligned} R_{ch}(c f(t)) &= \int_0^T (c f(t)) \cosh(pt) dt \\ &= c \int_0^T f(t) \cosh(pt) dt \\ &= c R_{ch}(f(t)). \end{aligned}$$

$$3. \quad \text{Scaling: If } R_{ch}(f(t)) = F_C(p, T), \text{ then } R_{ch}(f(at)) = \frac{F_C\left(\frac{p}{a}, aT\right)}{a}$$

Proof: Let $R_{ch}(f(t)) = F_C(p, T)$, then

$$\begin{aligned} R_{ch}(f(at)) &= \int_0^T f(at) \cosh(pt) dt \\ &= \frac{\int_0^T (f(x)) \cosh\left(\frac{xp}{a}\right) dx}{a} \\ &= \frac{F_C\left(\frac{p}{a}, aT\right)}{a} \end{aligned}$$

VIII. Discussion and Conclusion:

Unlike the usual Laplace transform of a function $f(t)$, there is no restriction needed on the transform variable p for the existence of $R_{ch}(f(t))$ and $R_{sh}(f(t))$. Further, the existence of $R_{ch}(f(t))$ and $R_{sh}(f(t))$ does not require exponential order property of a function $f(t)$. If a function $f(t)$ has the usual Laplace transform, then it also has the RAM Finite Sine Hyperbolic transform and RAM Finite Cosine Hyperbolic transform. In other words, if $L(f(t))$ exists, then $R_{ch}(f(t))$ and $R_{sh}(f(t))$ exists as shown below. We have

$$\begin{aligned} L(f(t)) &= \int_0^\infty f(t) e^{-pt} dt \\ &= \int_0^T f(t) \cosh(pt) dt - \int_0^T f(t) \sin(pt) dt + \int_T^\infty f(t) e^{-pt} dt \\ &= R_{ch}(f(t)) - R_{sh}(f(t)) + \int_T^\infty f(t) e^{-pt} dt. \end{aligned}$$

Since $L(f(t))$ exists, all the three integrals on R.H.S. exist. Hence, if $L(f(t))$ exists then $R_{ch}(f(t))$ and $R_{sh}(f(t))$ exists but converse is not necessarily true. This can be shown by an example. It is well known that the usual Laplace transform of $f(t) = e^{at}$, for $a > 0$, does not exist but $R_{ch}(e^{at})$ and $R_{sh}(e^{at})$ both exists.

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