

Symmetric Skew 4-Reverse Derivations on Semi Prime Rings

Dr. C. Jaya Subba Reddy¹, S. Vasantha Kumar², K.Subbarayudu³

^{1,2,3}Department of Mathematics, S.V.University, Tirupati -517502, Andhra Pradesh, India.

Abstract: In this paper we introduce the notation of symmetric skew 4-reverse derivation of semiprime ring and we consider R be a non-commutative 2,3-torsion free semiprime ring, I be a non zero two sided ideal of R , α be an anti-automorphism of R , and $D: R^4 \rightarrow R$ be a symmetric skew 4-reverse derivation associated with the anti-automorphism α . Suppose that the trace function f is commuting on I and $[f(y), \alpha(y)] \in Z$, for all $y \in I$, then $[f(y), \alpha(y)] = 0$, for all $y \in I$.

Keywords: Semi prime ring, Derivation, Bi derivation, Reverse derivation, Symmetric Skew 3-derivation, Symmetric Skew 4-derivation, Symmetric skew 4-Reverse derivation and Anti-automorphism.

I. Introduction

Bresar and Vukman [2] have introduced the notation of a reverse derivations and Samman and Alyamani [6] have studied some properties of semi prime rings with reverse derivations. The study of centralizing and commuting mappings on prime rings was initiated by the result of Posner [5] which states that the existence of a nonzero centralizing derivation on a prime ring implies that the ring has to be commutative. Vukman [7, 8] investigated symmetric bi derivation on prime and semi prime rings in connection with centralizing mappings. A.Fosner [1] have studied some results in symmetric skew 3-derivations with prime rings and semiprimerings. Recently Faiza Shujat, Abuzaid Ansari [3] studied some results in symmetric skew 4-derivations in prime rings. C.Jaya Subba Reddy [4] have studied some results in symmetric skew 3-reverse derivations with semiprimerings. Motivated by the above work, in this paper we proved that under certain conditions of a semiprime ring with a nonzero symmetric skew 4-reverse derivations has to be commutative.

II. Preliminaries

Throughout the paper, R will represent a ring with a center Z and α an anti-automorphism of R . Let $n \geq 2$ be an integer. A ring R is said to be n -torsion free if for $x \in R$, $nx = 0$ implies $x = 0$. For all $x, y \in R$ the symbol $[x, y]$ will denote the commutator $xy - yx$. We make extensive use of basic commutator identities $[xy, z] = [x, z]y + x[y, z]$ and $[x, yz] = [x, y]z + y[x, z]$. Recall that a ring R is semi prime if $xRx = 0$ implies that $x = 0$. An additive map $d: R \rightarrow R$ is called derivation if $d(xy) = d(x)y + xd(y)$, for all $x, y \in R$, and it is called a skew derivation (α -derivation) of R associated with the anti-automorphism α if $d(xy) = d(x)y + \alpha(x)d(y)$, for all $x, y \in R$. An additive map $d: R \rightarrow R$ is called reverse derivation if $d(xy) = xd(y) + yd(x)$, for all $x, y \in R$, and it is called a skew reverse derivation of R associated with anti-automorphism α if $d(xy) = xd(y) + \alpha(y)d(x)$, for all $x, y \in R$.

Before starting our main theorem, let us give some basic definitions and well known results which we will need in our further investigation.

Let D be a symmetric 4-additive map of R , then obviously

$$D(-p, q, r, s) = -D(p, q, r, s), \text{ for all } p, q, r, s \in R. \quad (1)$$

Namely, for all $y, z \in R$, the map $D(\dots, y, z): R \rightarrow R$ is endomorphism of the additive group of R .

The map $f: R \rightarrow R$ defined by $f(x) = D(x, x, x, x)$, $x \in R$ is called trace of D .

Note that f is not additive on R . But for all $x, y \in R$, we have

$$f(x + y) = [f(x) + 4D(x, x, x, y) + 6D(x, x, y, y) + 4D(x, y, y, y) + f(y)]$$

Recall that by (1), f is even function

More precisely, for all $p, q, r, s, u, v, w, x \in R$, we have

$$\begin{aligned} D(pu, q, r, s) &= pD(u, q, r, s) + \alpha(u)D(p, q, r, s), \\ D(p, qv, r, s) &= qD(p, v, r, s) + \alpha(v)D(p, q, r, s), \\ D(p, q, rw, s) &= rD(p, q, w, s) + \alpha(w)D(p, q, r, s), \\ D(p, q, r, sx) &= sD(p, q, r, x) + \alpha(x)D(p, q, r, s). \end{aligned}$$

Of course, if D is symmetric, then the above four relations are equivalent to each other.

Lemma 1: Let R be a prime ring and $a, b \in R$. If $a[x, b] = 0$ for all $x \in R$, then either $a = 0$ or $b \in Z$.

Proof: Note that

$$0 = a[xy, b] = ax[y, b] + a[x, b]y = ax[y, b] \text{ for all } x, y \in R.$$

Thus $aR[y, b] = 0$, $y \in R$, and, since R is prime, either $a = 0$ or $b \in Z$.

Theorem 1: Let R be a 2,3-torsion free non commutative semiprime ring and I be a nonzero ideal of R . Suppose α is an anti automorphism of R and $D: R^4 \rightarrow R$ is a symmetric skew 4-reverse derivation associated with α . Suppose that the trace function f is commuting on I and $[f(y), \alpha(y)] \in Z$, for all $y \in I$, then $[f(y), \alpha(y)] = 0$, for all $y \in I$.

Proof: Let $[f(y), \alpha(y)] \in Z$, for all $y \in I$. (2)

Linearization of (2) yields that

$$[f(x+y), \alpha(x+y)] \in Z, \text{ for all } x, y \in I.$$

$$[f(x+y), \alpha(x) + \alpha(y)] \in Z$$

By skew 4-derivation, we have

$$(f(x+y), \alpha(x) + \alpha(y)) = [f(x) + 4D(x, x, x, y) + 6D(x, x, y, y) + 4D(x, y, y, y) + f(y), \alpha(x) + \alpha(y)], \text{ for all } x, y \in I.$$

$$[f(x), \alpha(x)] + 4[D(x, x, x, y), \alpha(x)] + 6[D(x, x, y, y), \alpha(x)] + 4[D(x, y, y, y), \alpha(x)] + [f(y), \alpha(x)] + [f(x), \alpha(y)] + 4[D(x, x, x, y), \alpha(y)] + 6[D(x, x, y, y), \alpha(y)] + 4[D(x, y, y, y), \alpha(y)] + [f(y), \alpha(y)] \in Z, \text{ for all } x, y \in I. \quad (3)$$

From (2) & (3), we get

$$4[D(x, x, x, y), \alpha(x)] + 6[D(x, x, y, y), \alpha(x)] + 4[D(x, y, y, y), \alpha(x)] + [f(y), \alpha(x)] + [f(x), \alpha(y)] + 4[D(x, x, x, y), \alpha(y)] + 6[D(x, x, y, y), \alpha(y)] + 4[D(x, y, y, y), \alpha(y)] \in Z,$$

for all $x, y \in I$. (4)

Replacing y by $-y$ in (4) we have

$$\begin{aligned} -4[D(x, x, x, y), \alpha(x)] + 6[D(x, x, y, y), \alpha(x)] - 4[D(x, y, y, y), \alpha(x)] + [f(y), \alpha(x)] - [f(x), \alpha(y)] \\ + 4[D(x, x, x, y), \alpha(y)] - 6[D(x, x, y, y), \alpha(y)] + 4[D(x, y, y, y), \alpha(y)] \in Z, \end{aligned}$$

for all $x, y \in I$. (5) Comparing (4) and

(5) and using 2-torsion freeness of R , we get

$$4[D(x, x, x, y), \alpha(x)] + 4[D(x, y, y, y), \alpha(x)] + [f(x), \alpha(y)] + 6[D(x, x, y, y), \alpha(y)] \in Z, \text{ for all } x, y \in I. \quad (6)$$

Substitute $y+z$ for y in (6) and using (6), we get

$$4[D(x, x, x, y+z), \alpha(x)] + 4[D(x, y+z, y+z, y+z), \alpha(x)] + [f(x), \alpha(y+z)] + 6[D(x, x, y+z, y+z), \alpha(x)] + z, \text{ for all } x, y, z \in I.$$

$$\begin{aligned} 4[D(x, x, x, y), \alpha(x)] + 4[D(x, x, x, z), \alpha(x)] + 4[D(x, y, y, y), \alpha(x)] + 4[D(x, y, y, z), \alpha(x)] \\ + 4[D(x, y, z, y), \alpha(x)] + 4[D(x, y, z, z), \alpha(x)] + 4[D(x, z, y, y), \alpha(x)] + 4[D(x, z, y, z), \alpha(x)] \\ + 4[D(x, z, z, y), \alpha(x)] + 4[D(x, z, z, z), \alpha(x)] + [f(x), \alpha(y)] + [f(x), \alpha(z)] \\ + 6[D(x, x, y, y), \alpha(y)] + 6[D(x, x, y, z), \alpha(y)] + 6[D(x, x, z, y), \alpha(y)] \\ + 6[D(x, x, z, z), \alpha(y)] + 6[D(x, x, y, y), \alpha(z)] + 6[D(x, x, y, z), \alpha(z)] + 6[D(x, x, z, y), \alpha(z)] \\ + 6[D(x, x, z, z), \alpha(z)] \in Z. \end{aligned}$$

$$\begin{aligned} 12[D(x, y, y, z), \alpha(x)] + 12[D(x, y, z, z), \alpha(x)] + 12[D(x, x, y, z), \alpha(y)] + 6[D(x, x, z, z), \alpha(y)] \\ + 6[D(x, x, y, y), \alpha(z)] + 12[D(x, x, y, z), \alpha(z)] \in Z, \end{aligned}$$

for all $x, y, z \in I$. (7)

Replacing z by $-z$ in (7) and compare with (7), we obtain

$$\begin{aligned} -12[D(x, y, y, z), \alpha(x)] + 12[D(x, y, z, z), \alpha(x)] - 12[D(x, x, y, z), \alpha(y)] + 6[D(x, x, z, z), \alpha(y)] \\ - 6[D(x, x, y, y), \alpha(z)] + 12[D(x, x, y, z), \alpha(z)] \in Z \end{aligned}$$

$$2(12[D(x, z, y, y), \alpha(x)] + 12[D(x, x, y, z), \alpha(y)] + 6[D(x, x, y, y), \alpha(z)]) \in Z,$$

for all $x, y, z \in I$.

Using of 2-torsion free ring, we have

$$12[D(x, z, y, y), \alpha(x)] + 12[D(x, x, y, z), \alpha(y)] + 6[D(x, x, y, y), \alpha(z)] \in Z,$$

for all $x, y, z \in I$. (8)

Substitute $y+u$ for y in (8) and use (8) we get

$$12[D(x, z, y+u, y+u), \alpha(x)] + 12[D(x, x, y+u, z), \alpha(y+u)] + 6[D(x, x, y+u, y+u), \alpha(z)] \in Z, \text{ for all } x, y, z, u \in I.$$

$$\begin{aligned} 12[D(x, z, y, y), \alpha(x)] + 12[D(x, z, y, u), \alpha(x)] + 12[D(x, z, u, y), \alpha(x)] + 12[D(x, z, u, u), \alpha(x)] + \\ 12[D(x, x, y, z), \alpha(y)] + 12[D(x, x, u, z), \alpha(y)] + 12[D(x, x, y, z), \alpha(u)] + 12[D(x, x, u, z), \alpha(u)] + \\ 6[D(x, x, y, y), \alpha(z)] + 6[D(x, x, y, u), \alpha(z)] + 6[D(x, x, u, y), \alpha(z)] + 6[D(x, x, u, u), \alpha(z)] \in Z, \text{ for all } x, y, z, u \in I. \end{aligned}$$

$$24[D(x, z, y, u), \alpha(x)] + 12[D(x, x, y, z), \alpha(u)] + 12[D(x, x, u, z), \alpha(y)] + 12[D(x, x, y, u), \alpha(z)] \in Z, \text{ for all } x, y, z, u \in I. \quad (9)$$

Since R is a 2 and 3-torsion free and replacing y, u by x in (9), we have

$$24[D(x, z, x, x), \alpha(x)] + 12[D(x, x, x, z), \alpha(x)] + 12[D(x, x, x, z), \alpha(x)] + 12[D(x, x, x, x), \alpha(z)] \in Z, \text{ for all } x, z \in I.$$

$$48[D(x, x, x, z), \alpha(x)] + 12[D(x, x, x, x), \alpha(z)] \in Z, \text{ for all } x, z \in I.$$

$$4[D(x, x, x, z), \alpha(x)] + [f(x), \alpha(z)] \in Z, \text{ for all } x, z \in I. \quad (10)$$

Again replaced z by zx in (10) and using (10) we obtain

$$4[D(x, x, x, zx), \alpha(x)] + [f(x), \alpha(zx)] \in Z, \text{ for all } x, z \in I.$$

$$4[D(x, x, x, zx), \alpha(x)] + [f(x), \alpha(x)\alpha(z)] \in Z, \text{ for all } x, z \in I.$$

$$4[zf(x) + \alpha(x)D(x, x, x, z), \alpha(x)] + [f(x), \alpha(x)]\alpha(z) + \alpha(x)[f(x), \alpha(z)] \in Z,$$

for all $x, z \in I$.

$$4[z, \alpha(x)]f(x) + 4z[f(x), \alpha(x)] + 4\alpha(x)[D(x, x, x, z), \alpha(x)] + [f(x), \alpha(x)]\alpha(z) + \alpha(x)[f(x), \alpha(z)] \in Z, \text{ for all } x, z \in I.$$

$$\alpha(x)([f(x), \alpha(z)] + 4[D(x, x, x, z), \alpha(x)]) + (\alpha(z) + 4z)[f(x), \alpha(x)] + 4[z, \alpha(x)]f(x) \in Z, \text{ for all } x, z \in I. \quad (11)$$

Therefore, from (11), we get

$$[\alpha(x)([f(x), \alpha(z)] + 4[D(x, x, x, z), \alpha(x)])], \alpha(x)] + [(\alpha(z) + 4z)[f(x), \alpha(x)], \alpha(x)] +$$

$$4[[z, \alpha(x)]f(x), \alpha(x)] = 0, \text{ for all } x, z \in I \quad (12)$$

$$\alpha(x)([f(x), \alpha(z)] + 4[D(x, x, x, z), \alpha(x)]), \alpha(x)] + (\alpha(z) + 4z)[[f(x), \alpha(x)], \alpha(x)] + [\alpha(z) +$$

$$4z, \alpha(x)][f(x), \alpha(x)] + 4[[z, \alpha(x)], \alpha(x)]f(x) + 4[z, \alpha(x)][f(x), \alpha(x)] = 0, \text{ for all } x, z \in I.$$

$$\alpha(x)([f(x), \alpha(z)], \alpha(x)] + 4\alpha(x)[[D(x, x, x, z), \alpha(x)], \alpha(x)] + (\alpha(z) + 4z)[[f(x), \alpha(x)], \alpha(x)] +$$

$$[\alpha(z), \alpha(x)][f(x), \alpha(x)] + 4[z, \alpha(x)][f(x), \alpha(x)] + 4[[z, \alpha(x)], \alpha(x)]f(x) + 4[z, \alpha(x)][f(x), \alpha(x)] = 0, \text{ for all } x, z \in I.$$

$$\alpha(x)([f(x), \alpha(z)], \alpha(x)] + [\alpha(z), \alpha(x)][f(x), \alpha(x)] + [4z, \alpha(x)][f(x), \alpha(x)] + 4[[z, \alpha(x)], \alpha(x)]f(x) + [4z, \alpha(x)][f(x), \alpha(x)] = 0, \text{ for all } x, z \in I.$$

$$[(\alpha(z) + 8z), \alpha(x)][f(x), \alpha(x)] + 4[[z, \alpha(x)], \alpha(x)]f(x) = 0, \text{ for all } x, z \in I. \quad (13)$$

Replacing z by $[f(x), \alpha(x)]f(x)$ in (13), we get

$$[(\alpha([f(x), \alpha(x)]f(x)) + 8[f(x), \alpha(x)]f(x), \alpha(x)][f(x), \alpha(x)] + 4[[[f(x), \alpha(x)]f(x), \alpha(x)], \alpha(x)]f(x) =$$

0, for all $x \in I$.

$$[(\alpha(f(x))\alpha([f(x), \alpha(x)]), \alpha(x)][f(x), \alpha(x)] + 8[[f(x), \alpha(x)]f(x), \alpha(x)][f(x), \alpha(x)] +$$

$$4[[f(x), \alpha(x)][f(x), \alpha(x)] + [[f(x), \alpha(x)], \alpha(x)]f(x), \alpha(x)]f(x) = 0, \text{ for all } x \in I.$$

$$\alpha(f(x))[\alpha([f(x), \alpha(x)]), \alpha(x)][f(x), \alpha(x)] + [\alpha(f(x)), \alpha(x)]\alpha([f(x), \alpha(x)])[f(x), \alpha(x)] +$$

$$8[[f(x), \alpha(x)], \alpha(x)]f(x)[f(x), \alpha(x)] + 8[f(x), \alpha(x)][f(x), \alpha(x)][f(x), \alpha(x)] +$$

$$4[[f(x), \alpha(x)][f(x), \alpha(x)], \alpha(x)]f(x) = 0, \text{ for all } x \in I.$$

$$[\alpha(f(x)), \alpha(x)]\alpha([f(x), \alpha(x)][f(x), \alpha(x)]) + 8[f(x), \alpha(x)][f(x), \alpha(x)][f(x), \alpha(x)] +$$

$$4[f(x), \alpha(x)][[f(x), \alpha(x)], \alpha(x)]f(x) + 4[[f(x), \alpha(x)], \alpha(x)][f(x), \alpha(x)]f(x) = 0, \text{ for all } x \in I.$$

$$[\alpha(f(x)), \alpha(x)]\alpha([f(x), \alpha(x)][f(x), \alpha(x)]) + 8[f(x), \alpha(x)][f(x), \alpha(x)][f(x), \alpha(x)] = 0, \text{ for all } x \in I.$$

$$[\alpha(f(x)), \alpha(x)]\alpha[f(x), \alpha(x)][f(x), \alpha(x)] + 8[f(x), \alpha(x)]^3 = 0, \text{ for all } x \in I.$$

Since f is commutes on I , and we have 2, 3-torsion freeness of R , we have

$$2[f(x), \alpha(x)]^3 = 0$$

It follows that $(2[f(x), \alpha(x)])^2 R 2([f(x), \alpha(x)])^2 = 0$.

Since R is semiprime, we have

$$2[f(x), \alpha(x)]^2 = 0, \text{ for all } x \in I. \quad (14)$$

On the other hand, taking $z = x^2$ in equation (10), we get

$$4[D(x, x, x, x^2), \alpha(x)] + [f(x), \alpha(x^2)] \in Z, \text{ for all } x \in I.$$

$$4[xD(x, x, x, x) + \alpha(x)D(x, x, x, x), \alpha(x)] + [f(x), \alpha(x)\alpha(x)] \in Z, \text{ for all } x \in I.$$

$$4[xf(x) + \alpha(x)f(x), \alpha(x)] + \alpha(x)[f(x), \alpha(x)] + [f(x), \alpha(x)]\alpha(x) \in Z,$$

for all $x \in I$.

$$4[xf(x), \alpha(x)] + 4[\alpha(x)f(x), \alpha(x)] + 2\alpha(x)[f(x), \alpha(x)] \in Z, \text{ for all } x \in I.$$

$$4[x, \alpha(x)]f(x) + 4x[f(x), \alpha(x)] + 4\alpha(x)[f(x), \alpha(x)] + 4[\alpha(x), \alpha(x)]f(x) + 2\alpha(x)[f(x), \alpha(x)] \in Z, \text{ for all } x \in I.$$

$$6\alpha(x)[f(x), \alpha(x)] + 4x[f(x), \alpha(x)] + 4[x, \alpha(x)]f(x) \in Z, \text{ for all } x \in I. \quad (15)$$

Therefore, from equation (15), we get

$$[f(x), 6\alpha(x)[f(x), \alpha(x)] + 4x[f(x), \alpha(x)] + 4[x, \alpha(x)]f(x)] = 0, \text{ for all } x \in I.$$

$$[f(x), 6\alpha(x)[f(x), \alpha(x)]] + [f(x), 4x[f(x), \alpha(x)]] + [f(x), 4[x, \alpha(x)]f(x)] = 0$$

$$6\alpha(x)[f(x), [f(x), \alpha(x)]] + 6[f(x), \alpha(x)][f(x), \alpha(x)] + 4x[f(x), [f(x), \alpha(x)]] + 4[f(x), x][f(x), \alpha(x)] + 4[f(x), [x, \alpha(x)]]f(x) + 4[x, \alpha(x)][f(x), f(x)] = 0$$

$$6[f(x), \alpha(x)]^2 + 4[f(x), [x, \alpha(x)]]f(x) = 0, \text{ for all } x \in I.$$

$$6[f(x), \alpha(x)]^2 + 4[[f(x), x], \alpha(x)]f(x) = 0, \text{ for all } x \in I.$$

Since f is commuting on I and using equation (16), we get

$$6[f(x), \alpha(x)]^2 = 0, \text{ for all } x \in I.$$

We have 2-torsion freeness, we get

$$3[f(x), \alpha(x)]^2 = 0, \text{ for all } x \in I. \quad (17)$$

Comparing (14) and (17), we get

$$[f(x), \alpha(x)]^2 = 0, \text{ for all } x \in I.$$

Note that zero is the only nilpotent element in the center of semiprime ring.

$$\text{Thus, } [f(x), \alpha(x)] = 0, \text{ for all } x \in I.$$

$$[f(y), \alpha(y)] = 0, \text{ for all } y \in I.$$

This completes the proof.

Corollary 1: Let R be a 3!-torsion free prime ring, I be a non-zero ideal of R and α be an anti-automorphism of R . Suppose that there exists a non-zero symmetric skew 4-derivation $D: R^4 \rightarrow R$ associated with the anti-automorphism α such that the trace function f is commuting on I and $(f(x), \alpha(x)) \in Z$, for all $x \in I$, then $D = 0$.

Proof: From theorem 1, $[f(x), \alpha(x)] \in Z$, for all $x \in I$, then we have $[f(x), \alpha(x)] = 0$, for all $x \in I$. From [4, Theorem 1] states that $[f(x), \alpha(x)] = 0$, for all $x \in I$, then $D = 0$. Observing above two relations we concludes that $[f(x), \alpha(x)] \in Z$, for all $x \in I$, then $D = 0$.

References

- [1] Ajda Fosner: Prime and Semiprime rings with symmetric skew 3-derivations, *Aequat. Math.* 87(2014), 191-200.
- [2] Bresar.M. and Vukman.J: On some additive mappings in rings with involution, *Aequationes Math.* 38(1989), 178-185.
- [3] Faiza Shujat, Abuzaid Ansari: Symmetric skew 4-derivations on Prime rings, *J.Math.Comput.Sci.* 4(2014), No.4, 649-656.
- [4] Jaya Subba Reddy .C: Prime rings with symmetric skew 3-reverse derivations, International Journal of Mathematics and Computer Applications Research, Vol.4, Issue 6, (2014), 69-74.
- [5] Posner. E.C: Derivations in prime rings, *Proc. Amer. Math.Soc.* 8(1957), 1093-1100.
- [6] Samman.M. and Alyamani.N: Derivations and reverse derivations in semi prime rings, International Mathematical Forum, 2, No.39(2007), 1895-1902.
- [7] Vukman. J: Symmetric bi-derivations on prime and semi-prime rings, *Aequationes Math.* 38,(1989), 245-254.
- [8] Vukman. J: Two results concerning symmetric bi-derivations on prime rings, *Aequationes Math.* 40,(1990), 181-189.