

## On The Linear Systems over Non Commutative Rhotrices

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**Abstract:** Rhotrices  $P_n$ ,  $Q_n$  and  $R_n$  were considered with the binary operation of non-commutative method of rhotrix multiplication defined by Sani(2007) to study linear systems of the form  $P_n \circ Q_n = R_n$ . This work identified conditions necessary for the solvability of the system and also presented procedure for computing the square root of a rhotrix.

**Keywords:** Rhotrix; Linear system; Row-column multiplication

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### I. Introduction

A mathematical arrays that is in some way between two-dimensional vectors and 2x2dimensional matrices were suggested by Atanassov and Shannon [3]. As an extension to thisidea, Ajibade [1] introduced an object that lies between 2x2 dimensional matrices and3x3 dimensional matrices called 'rhotrix'. A rhotrix as given in [1] is of the form

$$R_3(\mathfrak{R}) = \left\{ \left\langle \begin{array}{ccc} a & & \\ b & c & d \\ e & & \end{array} \right\rangle : a, b, c, d, e \in \mathfrak{R} \right\}, \quad (1)$$

where  $a, b, d, e, c = h(R) \in \mathfrak{R}$  and  $h(R)$  is called the heart of a rhotrix  $R$ . A rhotrix of the form (1) is called based rhotrix, which is rhotrix of base three. It was also mentioned in [1] that a

rhotrix can be extended to n-dimension. A rhotrix of size  $n$  denoted by  $R(n)$  or  $R_n$ , we mean a rhomboidal array having  $\frac{1}{2}(n^2 + 1)$  entries and of size  $n \in 2Z^+ + 1$ .

The algebra of rhotrices was presented in [1].

The operation of addition ( $+$ ), scalar multiplication ( $m$ ) and multiplication ( $\circ$ ) were also defined in [1] and is recorded as below:

Let  $R = \left\langle \begin{array}{ccc} a & & \\ b & h(R) & d \\ e & & \end{array} \right\rangle$  and  $Q = \left\langle \begin{array}{ccc} f & & \\ g & h(Q) & i \\ j & & \end{array} \right\rangle$  be any two rhotrices of size three and  $m$  a scalar, then

$$R + Q = \left\langle \begin{array}{ccc} a & & \\ b & h(R) & d \\ e & & \end{array} \right\rangle + \left\langle \begin{array}{ccc} f & & \\ g & h(Q) & i \\ j & & \end{array} \right\rangle = \left\langle \begin{array}{ccc} a + f & & \\ b + g & h(R) + h(Q) & d + i \\ e + j & & \end{array} \right\rangle, \quad (2)$$

$$mR = m \left\langle \begin{array}{ccc} a & & \\ b & h(R) & d \\ e & & \end{array} \right\rangle = \left\langle \begin{array}{ccc} ma & & \\ mb & mh(R) & md \\ me & & \end{array} \right\rangle, \quad (3)$$

and

$$R \circ Q = \left\langle \begin{matrix} a \\ b & h(R) & d \\ e \end{matrix} \right\rangle \circ \left\langle \begin{matrix} f \\ g & h(Q) & i \\ j \end{matrix} \right\rangle = \left\langle \begin{matrix} ah(Q) + fh(R) \\ bh(Q) + gh(R) & h(R)h(Q) & dh(Q) + ih(R) \\ eh(Q) + jh(R) \end{matrix} \right\rangle. \quad (4)$$

Sani (2007) extended the work of Sani (2004) to rhotrices of size  $n$  and gave the following proposition:  
Let  $R(n)$  and  $S(n)$  be rhotrices of size  $n$ , then the product of  $R(n)$  and  $S(n)$

$$\begin{aligned} R(n) \circ S(n) &= \left\langle a_{ij}, c_{kl} \right\rangle \circ \left\langle b_{ij}, d_{kl} \right\rangle \\ &= \left\langle \sum_{i,j=1}^t (a_{i,j} \cdot b_{i,j}), \sum_{k,l=1}^{t-1} (c_{k,l} \cdot d_{k,l}) \right\rangle, \quad (5) \\ &\text{where } t = \frac{1}{2}(n^2 + 1) \end{aligned}$$

Thus,  $R(n)$  and  $S(n)$  can be expressed as in Equation (5) and (6) respectively.

$$R(n) = \left\langle a_{i,j}, c_{k,l} \right\rangle = \left\langle \begin{matrix} & & & & a_{1,1} \\ & & & & a_{2,1} & c_{1,1} & a_{1,2} \\ & & a_{3,1} & c_{2,1} & a_{2,1} & c_{1,2} & a_{1,3} \\ \dots & \dots \\ a_{t,1} & \dots & a_{1,t} \\ \dots & \dots \\ & & a_{t,t-2} & c_{t-1,t-2} & a_{t-1,t-1} & c_{t-2,t-1} & a_{t-2,t} \\ & & a_{t,t-1} & c_{t-1,t-1} & a_{t-2,t} \\ & & & & a_{t,t} \end{matrix} \right\rangle \quad (6)$$

and

$$S(n) = \left\langle b_{i,j}, d_{k,l} \right\rangle = \left\langle \begin{matrix} & & & & b_{1,1} \\ & & & & b_{2,1} & d_{1,1} & b_{1,2} \\ & & b_{3,1} & d_{2,1} & b_{2,1} & d_{1,2} & b_{1,3} \\ \dots & \dots \\ b_{t,1} & \dots & b_{1,t} \\ \dots & \dots \\ & & b_{t,t-2} & d_{t-1,t-2} & b_{t-1,t-1} & d_{t-2,t-1} & b_{t-2,t} \\ & & b_{t,t-1} & d_{t-1,t-1} & b_{t-2,t} \\ & & & & b_{t,t} \end{matrix} \right\rangle. \quad (7)$$

The elements  $a_{i,j} (i, j = 1, 2, \dots, t)$  and  $c_{k,l} (k, l = 1, 2, \dots, t - 1)$  are called the major and minor entries of  $R(n)$  respectively. Similarly, The elements  $b_{i,j} (i, j = 1, 2, \dots, t)$  and  $d_{k,l} (k, l = 1, 2, \dots, t - 1)$  are the major and minor entries of  $S(n)$  respectively.

Also Sani (2007), generalized the definition of the transpose, determinant, identity and inverse of rhotrix  $R(n)$  of size  $n$ , (provided  $R(n) \neq 0$ ). Sani (2007) further established some interesting relationships between invertible  $n$ -size rhotrices and invertible  $t \times t$  dimensional matrices, where  $t = \frac{1}{2}(n+1), n \in 2Z^+ + 1$ .

This paper shall adopt the row-column method of rhotrix multiplication proposed by Sani to present Linear systems and their conditions for solvability.

### 2.0 Basic properties

This paper presents a summary of some basic properties of rhotrices.

Let  $P_n, Q_n$  and  $R_n$  be rhotrices of the same dimension  $n$ , let  $+$  and  $\circ$  be the usual addition and the row-column method of rhotrix multiplication respectively, then the following is true for rhotrices over a field  $\mathfrak{R}$  and  $\alpha \in \mathfrak{R}$

$$P_n + 0 = 0 + P_n = P_n$$

$$P_n + R_n = R_n + P_n$$

$$(P_n + Q_n) + R_n = P_n + (Q_n + R_n)$$

$$\alpha(P_n + Q_n) = \alpha P_n + \alpha Q_n$$

$$(P_n \circ Q_n) \circ R_n = P_n \circ (Q_n \circ R_n)$$

### II. Linear systems of Non-commutative rhotrices

Aminu, [2] presented a study of Linear systems over rhotrices, considering the heart-based method of rhotrix multiplication as the binary operation. This paper investigates linear system under the binary operation defined by Sani (2004) for  $n$ -dimensional rhotrices.

Let us assume, without loss of generality that rhotrices  $P_n, Q_n$  and  $R_n$  are base rhotrices, that is, rhotrices of dimension 3.

Consider the linear system

$$P_3 \circ Q_3 = R_3$$

$$\begin{aligned}
 P_3 \circ Q_3 &= \left\langle \begin{array}{ccc} p_1 & & \\ p_2 & h(P) & p_3 \\ & p_4 & \end{array} \right\rangle \circ \left\langle \begin{array}{ccc} q_1 & & \\ q_2 & h(Q) & q_3 \\ & q_4 & \end{array} \right\rangle \\
 &= \left\langle \begin{array}{ccc} p_1q_1 + p_3q_2 & & \\ p_2q_1 + p_4q_2 & h(R) \times h(Q) & p_1q_3 + p_3q_4 \\ p_2q_3 + p_4q_4 & & \end{array} \right\rangle = \left\langle \begin{array}{ccc} r_1 & & \\ r_2 & h(R) & r_3 \\ & r_4 & \end{array} \right\rangle
 \end{aligned}$$

This is equivalent to

$$\left. \begin{aligned}
 p_1q_1 + p_3q_2 &= r_1 \\
 p_2q_1 + p_4q_2 &= r_2 \\
 p_1q_3 + p_3q_4 &= r_3 \\
 p_2q_3 + p_4q_4 &= r_4 \\
 h(P) \times h(Q) &= h(R)
 \end{aligned} \right\} \tag{8}$$

Solving (8) yields,

$$\left. \begin{aligned}
 q_1 &= \frac{1}{|P|} (p_4r_1 - p_3r_2) \\
 q_2 &= \frac{1}{|P|} (p_1r_2 - p_2r_1) \\
 q_3 &= \frac{1}{|P|} (p_4r_3 - p_3r_4) \\
 q_4 &= \frac{1}{|P|} (p_1r_4 - p_2r_3) \\
 h(Q) &= \frac{h(R)}{h(P)}, \frac{1}{|P|} \neq 0
 \end{aligned} \right\} \tag{9}$$

**III. Proposition**

Let  $P_n, Q_n$  and  $R_n$  be rhotrices of the same dimension  $n$  over reals, then the system  $P_n \circ Q_n = R_n$  has a unique solution if and only if  $\det(P_n) \neq 0$  and  $\det(R_n) \neq 0$ .

Proof:

Suppose  $\det(P_n) \neq 0$  and  $\det(R_n) \neq 0$ , it follows from (7) that  $\det(P_n) \neq 0$  and  $\det(R_n) \neq 0$ .

$$\Leftrightarrow h(Q) = \frac{h(R)}{h(P)} \text{ and } q_i = \begin{cases} p_4 r_i + p_3 r_{i+1} : \text{if } i \in (2N - 1) \\ p_1 r_i + p_2 r_{i+1} : \text{if } i \in 2N \end{cases}$$

This completes the proof.

It can easily be deduced from proposition 3.1 above that the necessary and sufficient condition for obtaining an exact solution to the linear system  $P_n \circ Q_n = R_n$  is that  $\det(\langle P_{i,j}, P_{k,l} \rangle) \neq 0$  and  $\det(\langle R_{i,j}, R_{k,l} \rangle) \neq 0$ .

**Proposition 3.2**

Let  $P_n, Q_n$  and  $R_n$  be rhotrices of the same dimension  $n$  over reals, then the system  $P_n \circ Q_n = R_n$  has no solution if and only if  $\det(P_n) = 0$  and  $\det(R_n) \neq 0$ .

**Proposition 3.3**

Let  $P_n, Q_n$  and  $R_n$  be rhotrices of the same dimension  $n$  over reals, then the system  $P_n \circ Q_n = R_n$  has a infinite solution if and only if  $\det(P_n) = 0$  and  $\det(R_n) = 0$ .

**IV. Concrete example**

Consider the linear system of rhotrices  $P_3 \circ Q_3 = R_3$  where  $P_3 = \left\langle \begin{matrix} 2 \\ 1 & 3 & 5 \\ 4 \end{matrix} \right\rangle$  and  $R_3 = \left\langle \begin{matrix} 4 \\ 3 & 4 & 2 \\ 5 \end{matrix} \right\rangle$

Find the rhotrix  $Q_3$  such that  $P_3 \circ Q_3 = R_3$ .

Using (9), we find the rhotrix  $Q_3$

$$\left. \begin{aligned} q_1 &= \frac{1}{|P|} (p_4 r_1 - p_3 r_2) = \frac{1}{3} (4 \cdot 4 - 5 \cdot 3) = \frac{1}{3} \\ q_2 &= \frac{1}{|P|} (p_1 r_2 - p_2 r_1) = \frac{1}{3} (2 \cdot 3 - 1 \cdot 4) = \frac{2}{3} \\ q_3 &= \frac{1}{|P|} (p_4 r_3 - p_3 r_4) = \frac{1}{3} (4 \cdot 2 - 5 \cdot 5) = \frac{-17}{3} \\ q_4 &= \frac{1}{|P|} (p_1 r_4 - p_2 r_3) = \frac{1}{3} (2 \cdot 5 - 1 \cdot 2) = \frac{8}{3} \\ h(Q) &= \frac{h(R)}{h(P)} = \frac{4}{3} \end{aligned} \right\} \quad (10)$$

Hence, the rhotrix  $Q_3 = \left\langle \begin{array}{ccc} & \frac{1}{3} & \\ \frac{1}{3} & \frac{4}{3} & \frac{-17}{3} \\ & \frac{8}{3} & \end{array} \right\rangle$ .

### V. Conclusion

In this paper the necessary and sufficient conditions for the solvability of linear system over rhotrices using rhotrix multiplication method proposed in [4] was developed. These conditions depend on the determinant of the respective rhotrices. A concrete example was given to verify the work.

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